

# CrystalBall: Statically Analyzing Runtime Behavior via Deep Sequence Learning



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# Introduction

- Why analyze runtime behavior?
- How to analyze it for software lifecycle? – Hot Paths (1 in a million)
- Path profiling:
  - Dynamic Profiling:  
Digital Mars C++
  - Group functions that call each other
  - Static Profiling:  
Predict runtime behavior before the program runs
  - Applications - Branch Prediction, Trace formation, Basic Block placement optimization

# Why not Dynamic Profiling?

- Needs representative production environment
- Computationally Expensive
- In for a penny, in for a pound

# Static Profiling – CrystalBall

- Program behavior is latent within instructions
- Higher the quality of static analysis => better runtime prediction
- Can leverage large amount of data
- Language independent – uses Intermediate Representation (IR)
- IR – Semantic + Low - level Ops
  - Compilers - GCC, LLVM (Low Level Virtual Machine)
- Sequence of blocks => use RNN

# Intermediate Representation

C++ Function -

```
int mul_add(int x, int y, int z){  
    return x * y + z;  
}
```

IR -

```
define i32 @mul_add(i32 %x, i32 %y, i32 %z) {  
    entry:  
        %tmp = mul i32 %x, %y  
        %tmp2 = add i32 %tmp, %z  
        ret i32 %tmp2  
}
```

# Basic Block

## Source Code:

```
w = 0;  
x = x + y;  
y = 0;  
if ( x > z ) {  
    y = x;  
    x++;  
}  
else{  
    y = z;  
    z++;  
}  
w = x + z;
```

## Basic Blocks:

```
w = 0;  
x = x + y;  
y = 0;  
if ( x > z )
```

```
    y = x;  
    x++;
```

```
    y = z;  
    z++;
```

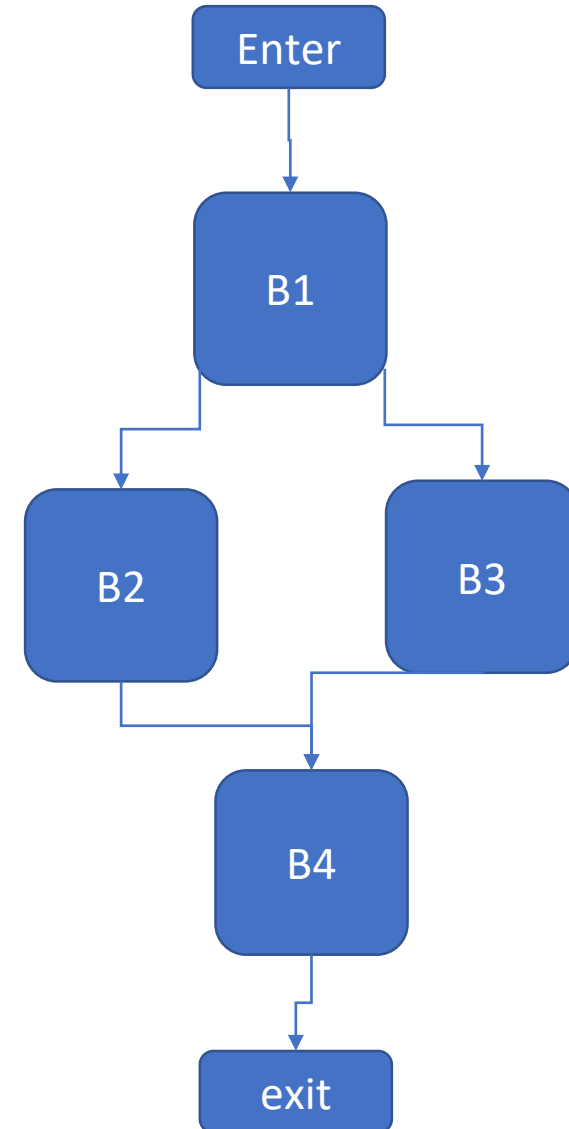
```
    w = x + z;
```

**B1**

**B2**

**B3**

**B4**



# Ball Larus Path Profiling

- Convert each function to Directed Acyclic Graph (DAG)
- Back edges are removed in DFS
- Unique sum of edge weight for a path

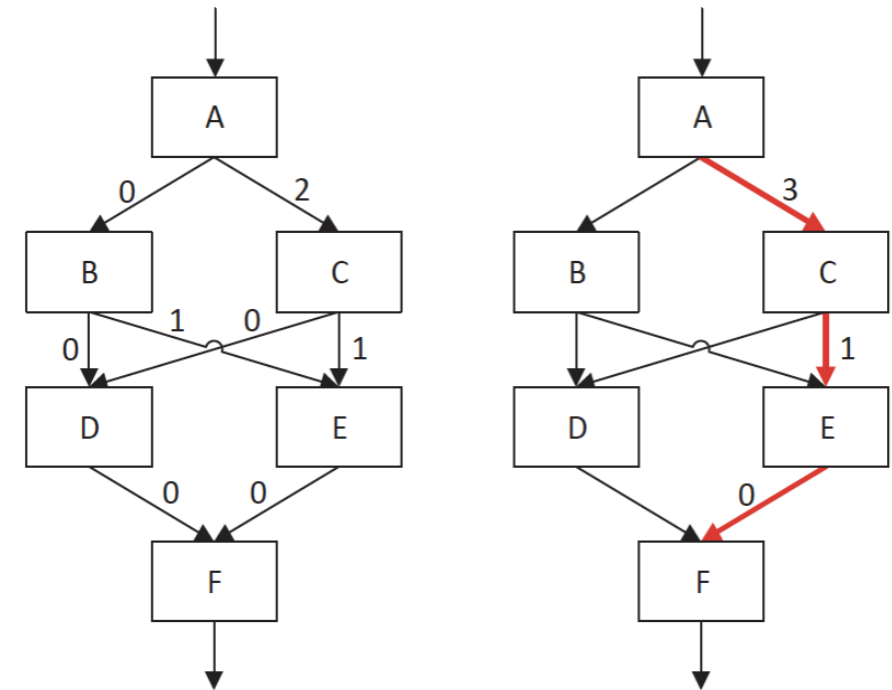


Fig. 1: Example of function path enumeration using Ball-Larus algorithm (left - edge weights between basic blocks, right - example of path reconstruction)

# Performance Metrics

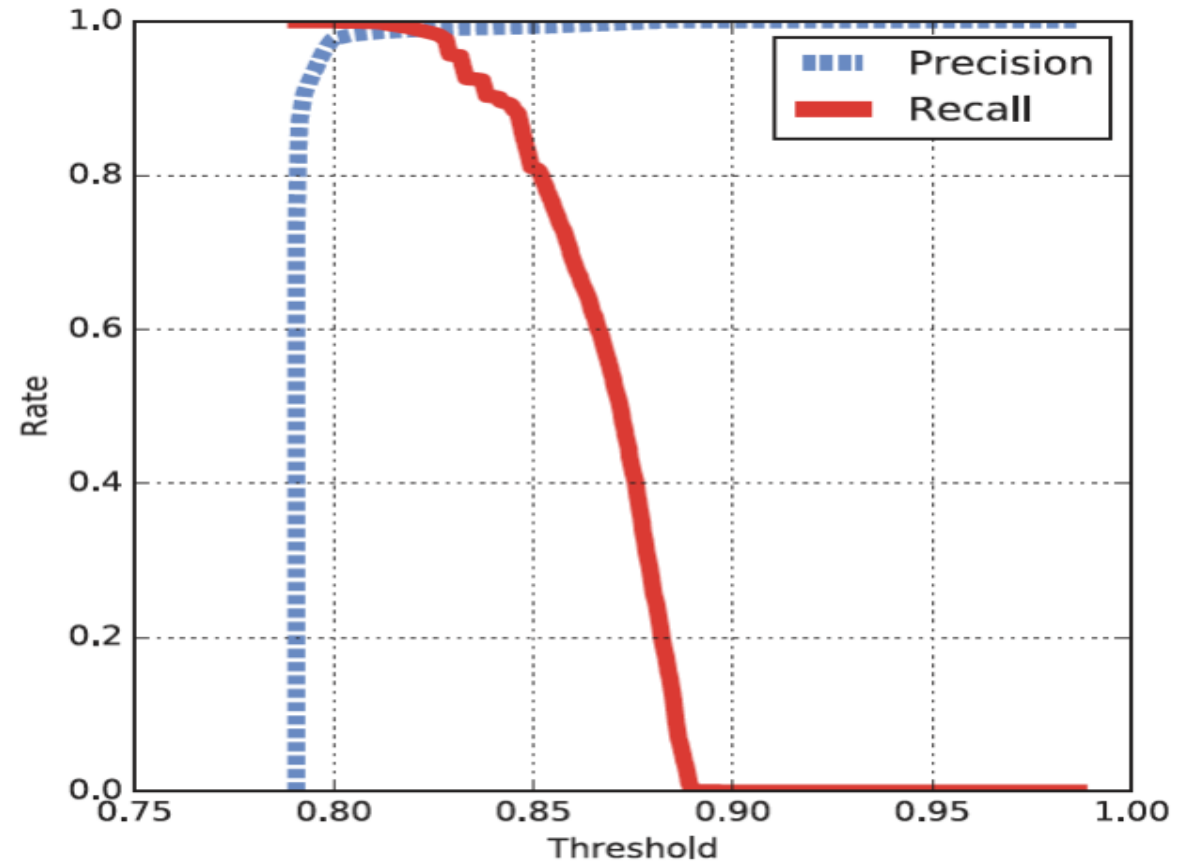
## Confusion Matrix:

		Predicted	
		+ve	-ve
Actual	+ve	TP	FN
	-ve	FP	TN

➤ Precision =  $TP / (TP + FP)$

➤ Recall =  $TP / (TP + FN)$

➤ F1 – measure =  $2 * Precision * Recall / (Precision + Recall)$





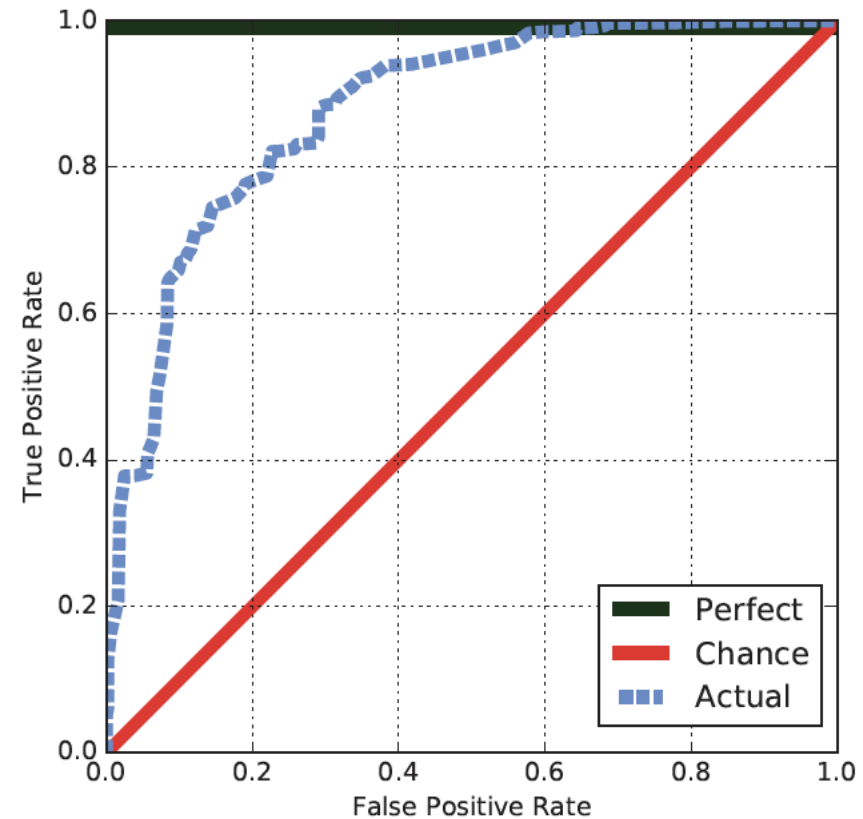
# Solution – AUROC (Area Under ROC)

$\text{TPR (Recall)} = \text{TP} / (\text{TP} + \text{FN})$

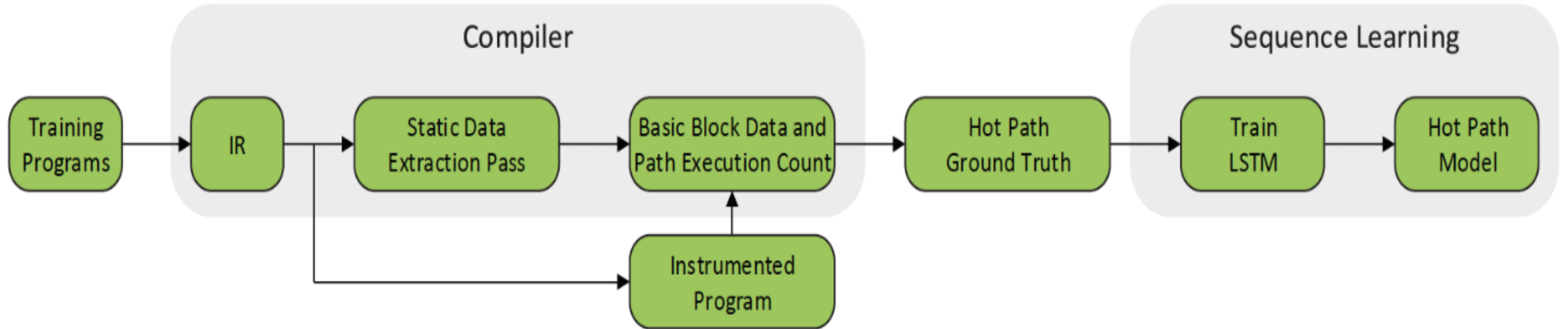
$\text{FPR} = \text{FP} / (\text{FP} + \text{TN})$

$\text{TPR} = \text{FPR (Random)}$

More area => better classifier



# Crystal Ball - Overview



# Crystal Ball - Implementation

- Data Collection: Using Profiling Instrumentation
- Static Data Extraction
  - Basic Block to feature vector
- Path Sampling –
  - Include all Hot Paths
  - Proportional Sampling for Cold paths
  - Equal number of Cold paths for every function (2000)
- Training: leave-one-program-out

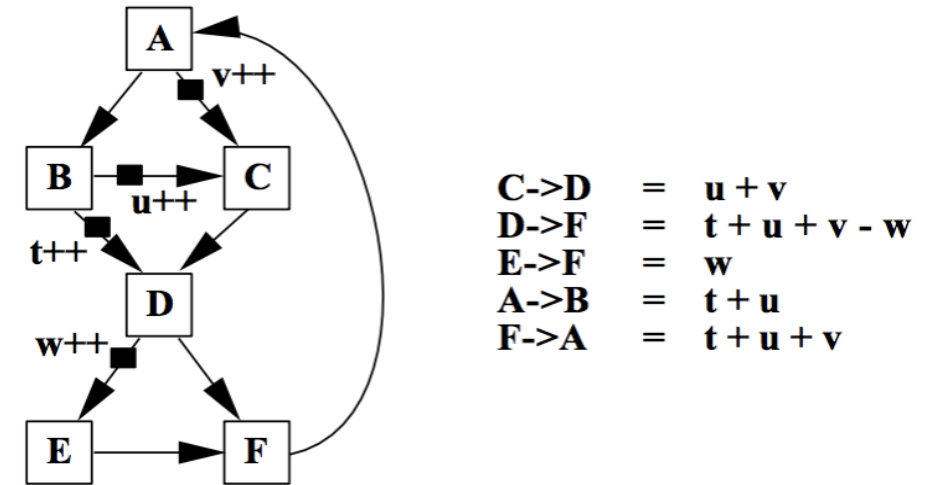
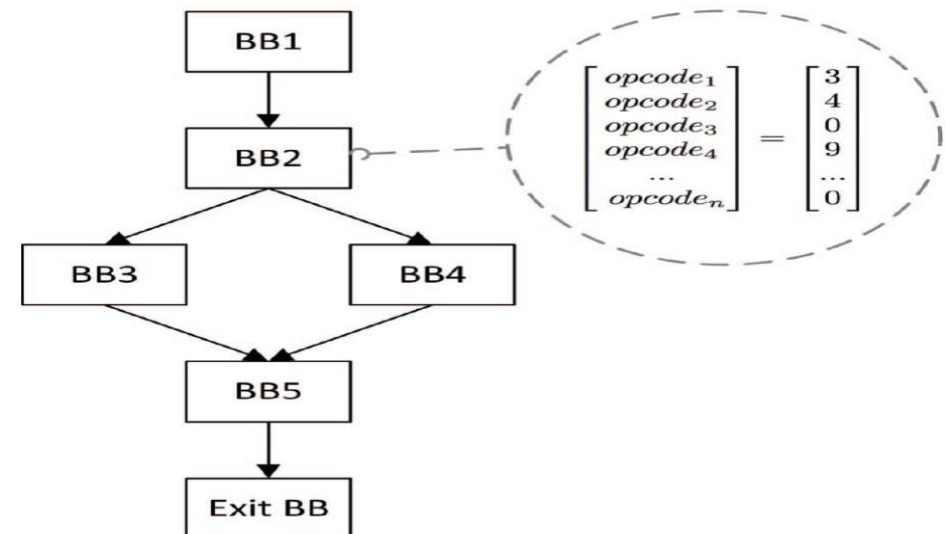
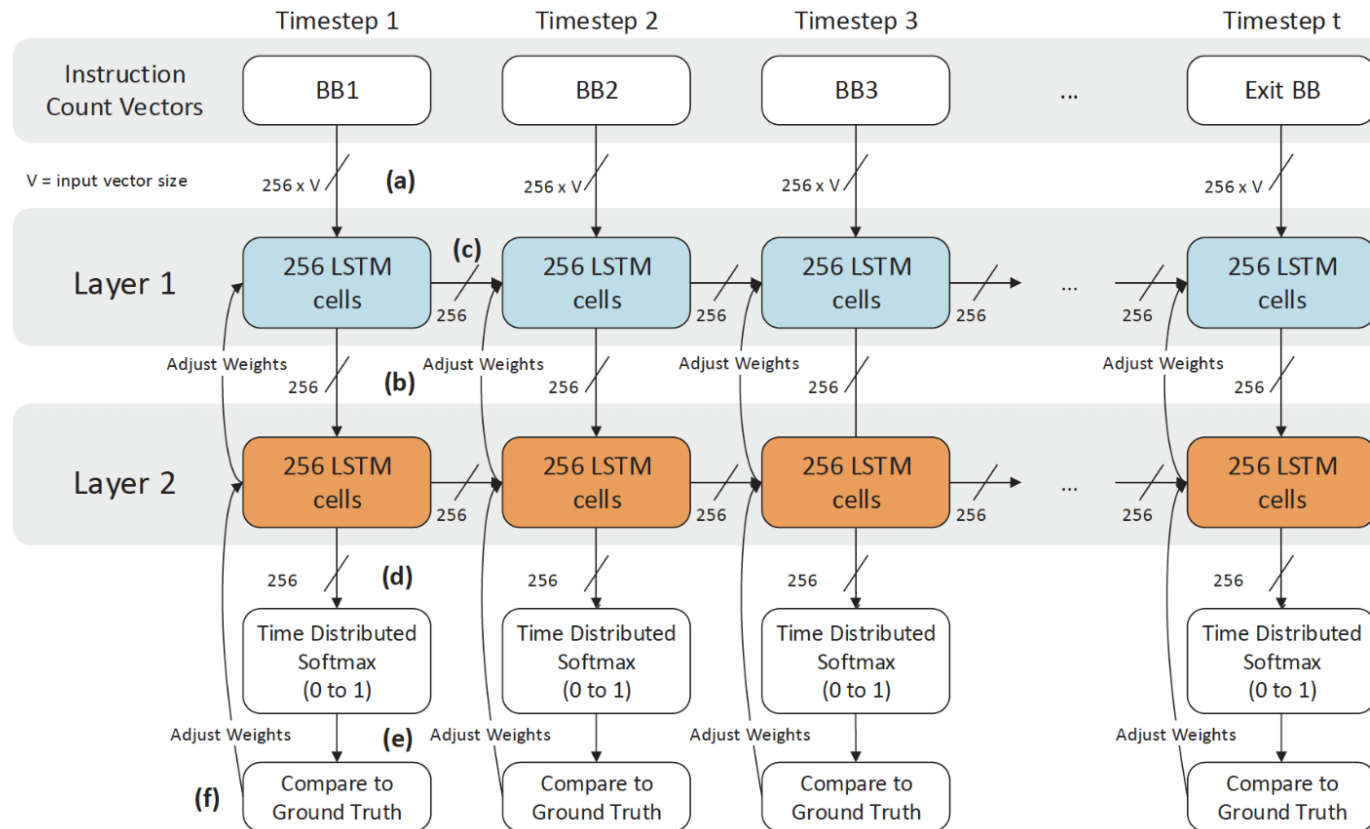


Figure 3. Instrumentation for edge profiling.



# LSTM Architecture



# Programs – SPEC CPU2000

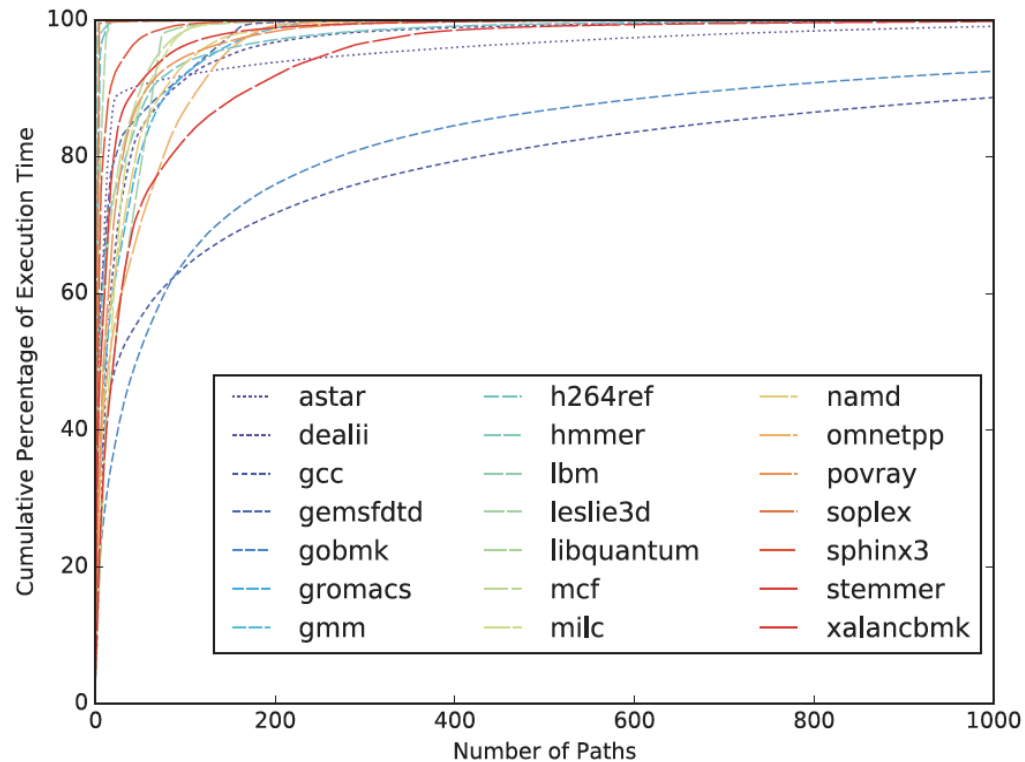


Fig. 9: Paths responsible for cumulative runtime

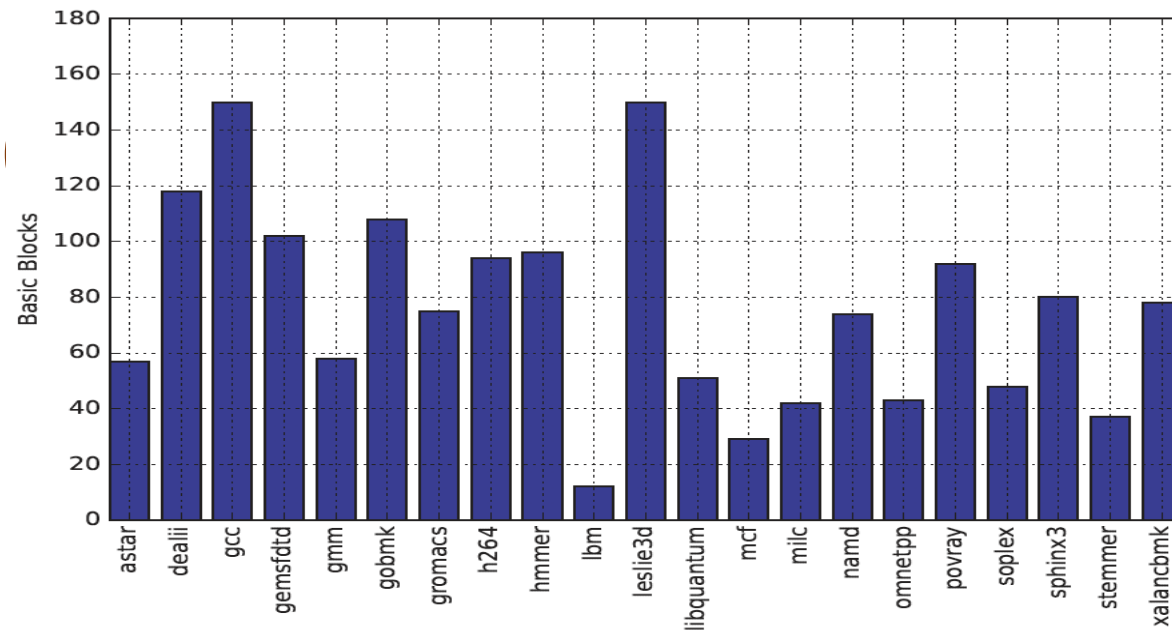


Fig. 11: Max path length by program

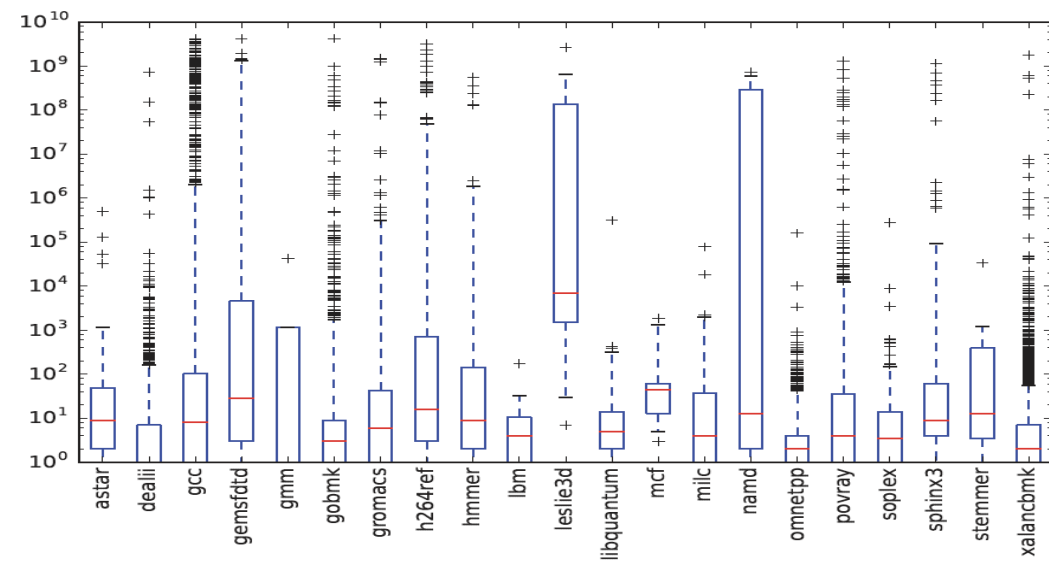


Fig. 10: Path counts per function

# Logistic regression - B&W static path classifier

- Removed Features specific to java code
- Added IR specific feature
- Hand crafted features
- One feature vector per path
- B& W model – 0.83 AUROC, Crystal Ball – 0.85

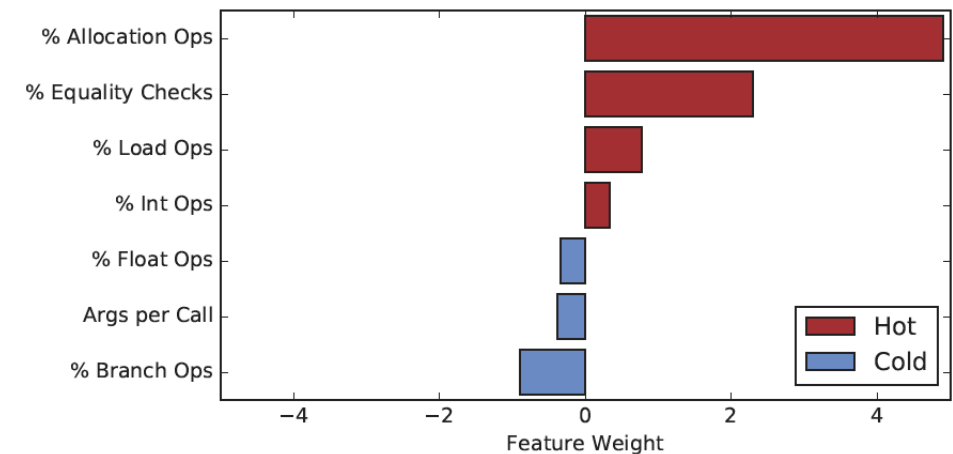


Fig. 15: Most important feature weights

# Results -

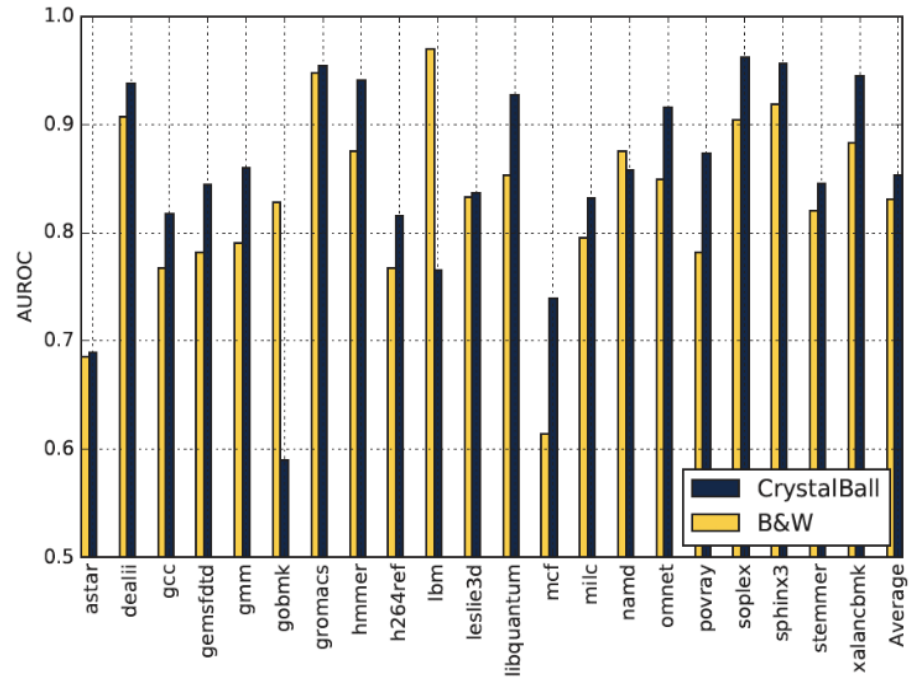


Fig. 12: AUROC by program

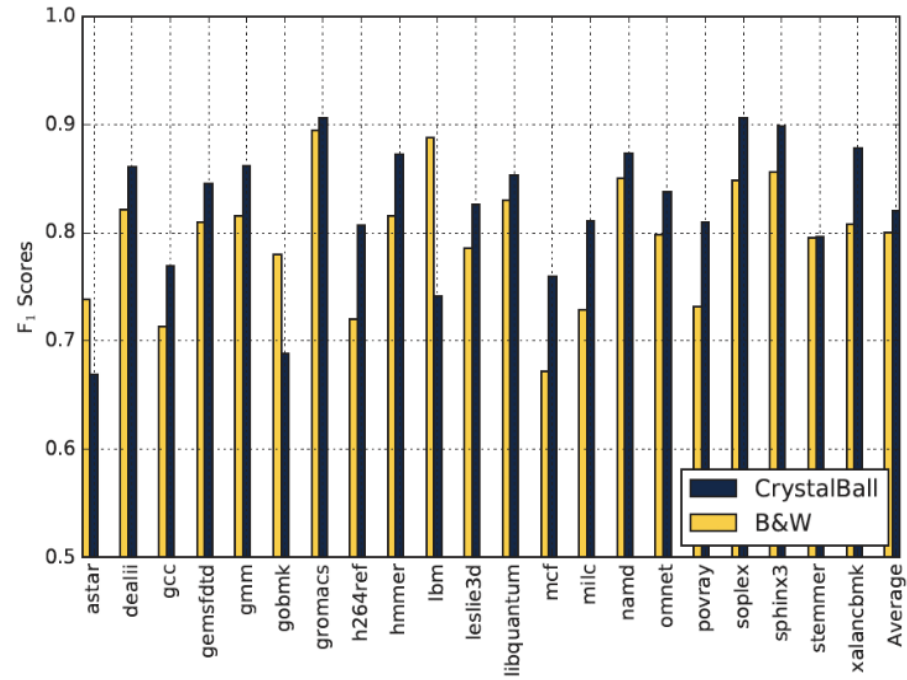


Fig. 13: F<sub>1</sub> scores by program

# Future Work/Caveats

- Although AUROC is best among the shown measure, greater AUROC value doesn't guarantee better model.
- Actual improvement in runtime behavior of a program?
- LSTM can just be used for feature extraction
- Novelty detection problem – SVM, K- Means
- Various Optimization flags and IR combination can be tried out.



Questions?