

Matlab script gauss.m: a few explanations

```
function [x] = gauss (A, b)
% function [x] = gauss (A, b)
% solves A x = b by Gaussian elimination
n = size(A,1) ;
A = [A,b];
for k=1:n-1
    for i=k+1:n
        piv = A(i,k) / A(k,k) ;
        A(i,k+1:n+1)=A(i,k+1:n+1)-piv*A(k,k+1:n+1);
    end
end
x = backsolv(A,A(:,n+1));
```

Function

```
function [x] = gauss (A, b)
% function [x] = gauss (A, b)
% solves A x = b by Gaussian elimination
...
```

- The file containing the above script should be called `gauss.m`.
- The syntax for `function` is simple:

```
function [Output-args] = func-name(Input-args)
% lines of comments
```

- Takes input arguments. Computes some values and returns them in the output arguments.

➤ The `gauss.m` script has 2 input arguments (A and b) and one output argument (x)

- `%` indicates a commented line. First few lines of comments after `function` header are echoed when you type

```
>> help func-name      For example >> help gauss
```

```

n = size(A,1) ;      % <-- n=Number of rows in matrix
A = [A,b];          % <-- Adds b as last column of A
                    % Now A contains augmented system.
                    % It has size n x (n+1)

```

```

for k=1:n-1          % Main loop in GE -- for each k
    for i=k+1:n      % sweep rows i=k+1 to i=n
        ...commands % these commands will each combine
    end              % row i with a multiple of row k
end

```

Example: Step $k = 3$ ($n = 6$)

```

for i=4:6
    piv=a(i,3)/a(3,3);
    row_i=row_i-piv*row_3;
end

```

| | | | | | | |
|---|---|---|---|---|---|---|
| * | * | * | * | * | * | * |
| 0 | * | * | * | * | * | * |
| 0 | 0 | * | * | * | * | * |
| 0 | 0 | * | * | * | * | * |
| 0 | 0 | * | * | * | * | * |
| 0 | 0 | * | * | * | * | * |

```
piv = A(i,k) / A(k,k) ;  
A(i,k+1:n+1)=A(i,k+1:n+1)-piv*A(k,k+1:n+1);
```

- The above: 1) computes the multiplier (pivot) to use in the elimination; 2) combines rows. Result = a zero in position (i, k) .
 - When combining row i with row k no need to deal with zeros in columns 1 to $k - 1$. Result will be zero.
 - Also we know $A(i, k)$ will be zero – can be skipped.
 - Result: need to combine rows from positions $k + 1$ to $n + 1$.
-

```
x = backsolve(A,A(:,n+1));
```

- The above invokes the back-solve script to solve the final system

THE ECHELON FORM [1.2]

The standard echelon form

A rectangular matrix is in **echelon form** (or **row echelon form**) if it has the following three properties:

1. All nonzero rows are above any rows of all zeros.
2. Each leading entry of a row is in a column to the right of the leading entry of the row above it.
3. All entries in a column below a leading entry are zeros.

➤ Each ■ is a **nonzero** (leading) entry.

➤ A * can be a non-zero or a zero entry.

$$\begin{bmatrix} \blacksquare & * & * & * & * & * & * & * & * & * & * \\ 0 & 0 & \blacksquare & * & * & * & * & * & * & * & * \\ 0 & 0 & 0 & 0 & 0 & 0 & \blacksquare & * & * & * & * \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & \blacksquare & * \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

➤ A sort of ‘stretched’ (to the right) upper triangular form with structure of some columns repeated

➤ Ignore the formal definition for a moment - use intuition from Gaussian Elimination. Example:

$$\begin{array}{ccccc} 1 & -1 & 2 & -1 & 2 \\ 2 & -2 & 3 & -1 & 4 \\ 3 & -3 & 9 & -6 & 6 \end{array}$$

➤ 1st step of Gaussian Elimination yields:

$$\begin{array}{ccccc} 1 & -1 & 2 & -1 & 2 \\ 0 & \underline{0} & \boxed{-1} & 1 & 0 \\ 0 & \underline{0} & 3 & -3 & 0 \end{array}$$

← a_{22} is zero and pivoting does not help. Skip & go to 3rd column where $a_{23} = -1$:

➤ GE on rows 2 & 3:

➤ $row_3 := row_3 - (-3) * row_2$

Result: →

$$\begin{array}{ccccc} 1 & -1 & 2 & -1 & 2 \\ 0 & 0 & -1 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{array}$$

In words: Row Echelon algorithm is a variant of Gaussia Elimination (with pivoting).

- * Step k now has two indices: pivot row k and pivot column l . (At the start $k = 1, l = 1$.)
- * Step k : Try to eliminate entries $a_{k+1,l}, a_{k+2,l}, \dots, a_{m,l}$.
- * Do pivoting if necessary and try perform Gaussian Elimination.
- * If the sub-column is all zero, set $l := l + 1$ and repeat.

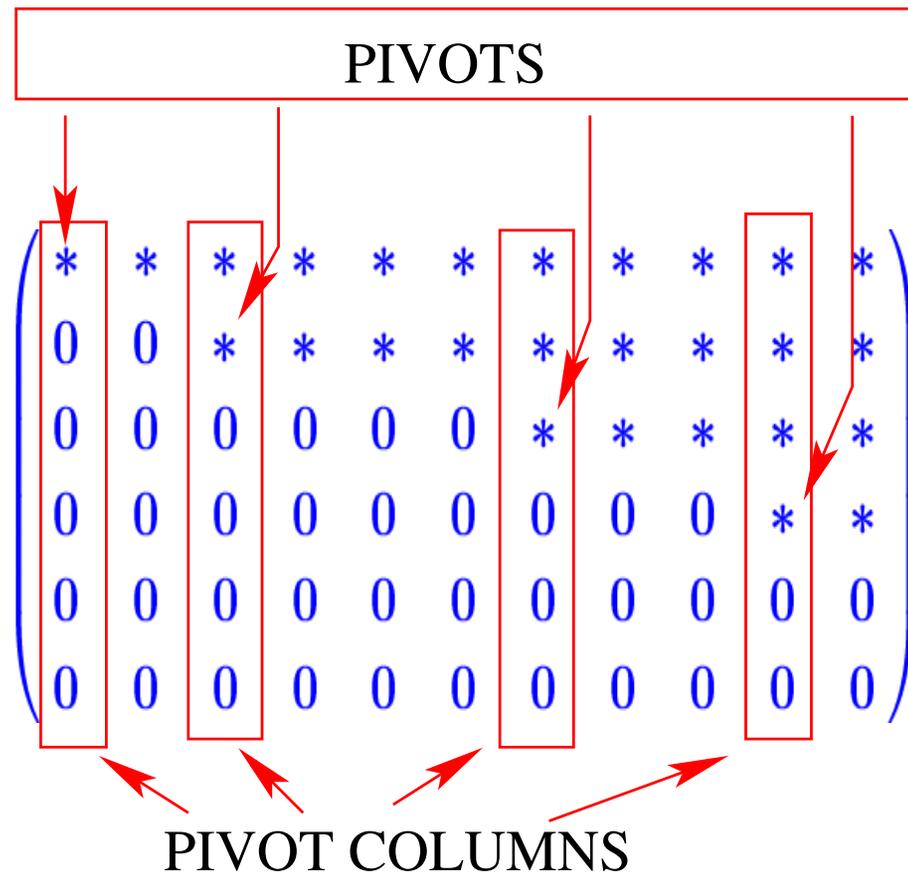
| | | | | | |
|-----|---|---|-----|---|---|
| | | | l | | |
| | * | * | * | * | * |
| k | 0 | 0 | 0 | * | * |
| | 0 | 0 | * | * | * |
| | 0 | 0 | * | * | * |

Case 1: swap row 2 and 3 (or 4). Then do GE step.

| | | | | | |
|-----|---|---|-----|-----------|---|
| | | | l | l_{new} | |
| | * | * | * | * | * |
| k | 0 | 0 | 0 | * | * |
| | 0 | 0 | 0 | * | * |
| | 0 | 0 | 0 | * | * |

Case 2: Reset l to $l = 4$. Continue.

Terminology: *Pivots, and pivot columns*



- Important in capturing the span of the columns of A (called the **range** of A - to be covered in detail later)

The reduced row echelon form

Definition : A matrix is in reduced echelon form (or reduced row echelon form) if: Matlab: rref

[1–3] It is in echelon form and, in addition,

4. The leading entry in each nonzero row is 1.

5. Each leading 1 is the only nonzero entry in its column.

$$\begin{bmatrix} 1 & * & 0 & * & * & * & 0 & * & * & 0 & * \\ & & 1 & * & * & * & 0 & * & * & 0 & * \\ & & & & & & 1 & * & * & 0 & * \\ & & & & & & & & & & 1 & * \end{bmatrix}$$

 How would you obtain the rref from the standard echelon form?

- Any nonzero matrix may be row reduced (i.e., transformed by elementary row operations) into more than one matrix in echelon form, using different sequences of row operations.
- However, the reduced echelon form one obtains from a matrix is unique:

Each matrix is row equivalent to one and only one reduced echelon matrix.

- Remember that the permissible row operations are:

1) Interchange; 2) addition; 3) scaling.

Pivot position

- A **pivot position** in a matrix A is a location in A that corresponds to a leading 1 in the reduced echelon form of A . A pivot column is a column of A that contains a pivot position.

$$\begin{bmatrix} \boxed{1} & * & 0 & * & * & * & 0 & * & * & 0 & * \\ & & \boxed{1} & * & * & * & 0 & * & * & 0 & * \\ & & & & & & \boxed{1} & * & * & 0 & * \\ & & & & & & & & & & \boxed{1} & * \end{bmatrix}$$

- In this example, the pivot columns are 1, 3, 7, and 10
- 📌 Find out how to get the pivot positions from matlab's `rref`

Example with standard echelon Form

Example: Row reduce the matrix A below to echelon form, and locate the pivot columns of A .

$$\begin{array}{ccccc} 0 & -3 & -6 & 4 & 9 \\ -1 & -2 & -1 & 3 & 1 \\ -2 & -3 & 0 & 3 & -1 \\ 1 & 4 & 5 & -9 & -7 \end{array}$$

Solution: The top of the leftmost nonzero column is the first pivot position. A nonzero entry, or pivot, must be placed in this position.

➤ Interchange rows 1 and 4 (note: in reality it is preferable to interchange rows 1 and 3. Why?)

↓ Pivot

| | | | | |
|----------|----|----|----|----|
| 1 | 4 | 5 | -9 | -7 |
| -1 | -2 | -1 | 3 | 1 |
| -2 | -3 | 0 | 3 | -1 |
| 0 | -3 | -6 | 4 | 9 |

↑ Pivot Column

- Create zeros below the pivot, 1, by adding multiples of the first row to the rows below → Next matrix:

| | | | | |
|----------|----------|----|-----|-----|
| 1 | 4 | 5 | -9 | -7 |
| 0 | 2 | 4 | -6 | -6 |
| 0 | 5 | 10 | -15 | -13 |
| 0 | -3 | -6 | 4 | 9 |

↑

Next pivot column

- Next pivot column: Add $-5/2$ times row 2 to row 3, and add $3/2$ times row 2 to row 4.

Result: →

| | | | | |
|---|---|---|----|----|
| 1 | 4 | 5 | -9 | -7 |
| 0 | 2 | 4 | -6 | -6 |
| 0 | 0 | 0 | 0 | 0 |
| 0 | 0 | 0 | -5 | 0 |

- Can't create a leading entry in column 3 → Move to col. 4.
Swap rows 3 & 4. Done.

| | | | | |
|---|---|---|----|----|
| 1 | 4 | 5 | -9 | -7 |
| 0 | 2 | 4 | -6 | -6 |
| 0 | 0 | 0 | -5 | 0 |
| 0 | 0 | 0 | 0 | 0 |

- Pivot columns: 1, 2, and 4.

- Recall: Algorithm to get **standard** row echelon form is a form of Gaussian elimination with pivoting

- Algorithm to get **reduced** row echelon form is a form of Gauss-Jordan elimination with pivoting

- Next: same example done with reduced form

Same example with reduced echelon Form

- Initial matrix below. First step same: swap rows 1 & 4

$$\begin{bmatrix} 0 & -3 & -6 & 4 & 9 \\ -1 & -2 & -1 & 3 & 1 \\ -2 & -3 & 0 & 3 & -1 \\ 1 & 4 & 5 & -9 & -7 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 4 & 5 & -9 & -7 \\ -1 & -2 & -1 & 3 & 1 \\ -2 & -3 & 0 & 3 & -1 \\ 0 & -3 & -6 & 4 & 9 \end{bmatrix}$$

- Next: Create zeros below the pivot, 1, by adding multiples of the first row to the rows below it.

→ Next matrix:

$$\begin{bmatrix} 1 & 4 & 5 & -9 & -7 \\ 0 & 2 & 4 & -6 & -6 \\ 0 & 5 & 10 & -15 & -15 \\ 0 & -3 & -6 & 4 & 9 \end{bmatrix}$$

- Scale 2nd row:

$$\begin{bmatrix} 1 & 4 & 5 & -9 & -7 \\ 0 & 1 & 2 & -3 & -3 \\ 0 & 5 & 10 & -15 & -15 \\ 0 & -3 & -6 & 4 & 9 \end{bmatrix}$$

- Next step: create zeros in column 2 [except position (2,2)]
- Move l to column 4; Swap rows 4, 5;

$$\begin{bmatrix} 1 & 0 & -3 & 3 & 5 \\ 0 & 1 & 2 & -3 & -3 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & -5 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & -3 & 3 & 5 \\ 0 & 1 & 2 & -3 & -3 \\ 0 & 0 & 0 & -5 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

Scale row 3

- Finally: create zeros in column 4 except position (3,4).

$$\begin{bmatrix} 1 & 0 & -3 & 3 & 5 \\ 0 & 1 & 2 & -3 & -3 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & -3 & 0 & 5 \\ 0 & 1 & 2 & 0 & -3 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

➤ Pivot positions: 1, 2, 4. They are (always) identical with those obtained from Standard Row Echelon form.

APPLICATIONS OF THE ECHELON FORM [1.3]

Solving a general linear system

Question: What are **all** the solutions of a linear system $[A, b]$

- Recall that we have 3 scenarios: 1) 0 solution; 2) infinitely many sols.; 3) exactly one solution.
- Set is called “**general solution**” or “**complete solution**”
- Answer provided by echelon form [reduced or standard]

Step 1 Form the augmented system $[A, b]$

| | | | | | | | | | | |
|---|---|---|---|---|---|---|---|---|---|---|
| * | * | * | * | * | * | * | * | * | * | * |
| * | * | * | * | * | * | * | * | * | * | * |
| * | * | * | * | * | * | * | * | * | * | * |
| * | * | * | * | * | * | * | * | * | * | * |
| * | * | * | * | * | * | * | * | * | * | * |
| * | * | * | * | * | * | * | * | * | * | * |

Step 2 Obtain the reduced echelon form.

➤ Result is something like:

| | | | | | | | | | | |
|---|---|---|---|---|---|---|---|---|---|---|
| 1 | * | 0 | * | * | * | 0 | * | * | 0 | * |
| | | 1 | * | * | * | 0 | * | * | 0 | * |
| | | | | | | 1 | * | * | 0 | * |
| | | | | | | | | | 1 | * |

Important: Solutions to this system same as those of $[A, b]$. So w'll find the solutions from this reduced system

 What can you say if the last column (RHS) happens to be a pivot column?

➤ Unknowns associated with pivots are called **basic**

➤ Others are called **free**

➤ In above example: **1, 3, 7, 10** are **basic**, **2, 4, 5, 6, 8, 9**, are **free**, and column **11** is the RHS (not a variable).

Step 3 Write solutions: solutions depend on parameters which are the free variables.

- Express basic variables in terms of the free variables
- For any values given to the free variables you will get a solution
- For example for the above picture: $x_{10} = b_4$;
 $x_7 = b_3 - \text{scalar} \cdot x_8 - \text{scalar} \cdot x_9$ etc..

 Find **general solution** when augmented matrix is:

| | | | | | | | |
|---|---|----|----|----|----|----|----|
| 1 | 2 | 0 | 0 | 1 | 0 | 0 | -2 |
| 1 | 2 | -1 | -2 | 2 | 2 | 3 | -3 |
| 1 | 2 | 2 | 4 | -3 | -4 | -4 | -6 |
| 0 | 0 | 1 | 2 | -3 | 0 | -5 | -3 |
| 1 | 2 | 0 | 0 | 2 | 0 | -1 | 1 |

➤ Get the reduced echelon form [use matlab!]

| | | | | | | | |
|----------|----------|----------|----------|----------|----------|-----------|-----------|
| 1 | 2 | 0 | 0 | 0 | 0 | 1 | -5 |
| 0 | 0 | 1 | 2 | 0 | 0 | -8 | 6 |
| 0 | 0 | 0 | 0 | 1 | 0 | -1 | 3 |
| 0 | 0 | 0 | 0 | 0 | 1 | -2 | 1 |
| 0 | 0 |

➤ Basic variables:

1, 3, 5, 6

➤ Free variables:

2, 4, 7

➤ Right-hand side : **8**

$$(1): \mathbf{x}_1 + 2\mathbf{x}_2 + \mathbf{x}_7 = -5$$

$$(2): \mathbf{x}_3 + 2\mathbf{x}_4 - 8\mathbf{x}_7 = 6$$

$$(3): \mathbf{x}_5 - \mathbf{x}_7 = 3$$

$$(4): \mathbf{x}_6 - 2\mathbf{x}_7 = 1$$

$$(5): 0 = 0 \text{ (vacuous)}$$

→

$$\mathbf{x}_1 = -5 - 2\mathbf{x}_2 - \mathbf{x}_7$$

$$\mathbf{x}_3 = 6 - 2\mathbf{x}_4 + 8\mathbf{x}_7$$

$$\mathbf{x}_5 = 3 + \mathbf{x}_7$$

$$\mathbf{x}_6 = 1 + 2\mathbf{x}_7$$

Note: It is also possible to use the standard (non-reduced) row-echelon form - Requires back substitution. Result is the same.

 What if last component of RHS is zero (i.e., $A(5, 8) = 0$)

 Below is the **standard** echelon form for the previous example. Find all solutions.

| | | | | | | | |
|---|---|---|---|----|----|----|----|
| 1 | 2 | 0 | 0 | 1 | 0 | 0 | -2 |
| 0 | 0 | 2 | 4 | -4 | -4 | -4 | -4 |
| 0 | 0 | 0 | 0 | -1 | 0 | 1 | -3 |
| 0 | 0 | 0 | 0 | 0 | 2 | -4 | 2 |
| 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

 Find all solutions for which x_4 and x_7 are zero.

 Among these find all solutions for which x_1 is zero.

 We seek 5 numbers x_1, \dots, x_5 such that their sum is 50, the sum of 3 of them (e.g. the odd-labeled ones) is 25, and the difference between the other 2 is 5. Write the equations to be satisfied and find the general solution.