

## GENERAL VECTOR SPACES AND SUBSPACES [4.1]

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## General vector spaces

- So far we have seen special spaces of vectors of  $n$  dimensions – denoted by  $\mathbb{R}^n$ .
- It is possible to define more general **vector spaces**

A vector space  $V$  over  $\mathbb{R}$  is a nonempty set with two operations:

- **Addition** denoted by '+'. For two vectors  $x$  and  $y$ ,  $x + y$  is a member of  $V$
- **Multiplication by a scalar** For  $\alpha \in \mathbb{R}$  and  $x \in V$ ,  $\alpha x$  is a member of  $V$ .

- In addition for  $V$  to be a vector space the following 8 axioms must be satisfied [note: order is different in text]

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1. Addition is commutative  $u + v = v + u$
2. Addition is associative  $u + (v + w) = (u + v) + w$
3.  $\exists$  zero vector denoted by  $0$  such that  $\forall u$ ,  $0 + u = u$
4. Any  $u$  has an opposite  $-u$  such that  $u + (-u) = 0$
5.  $1u = u$  for any  $u$
6.  $(\alpha\beta)u = \alpha(\beta u)$
7.  $(\alpha + \beta)u = \alpha u + \beta u$
8.  $\alpha(u + v) = \alpha u + \alpha v$

 Show that the zero vector in Axiom 3 is unique, and the vector  $-u$ , ('negative of  $u$ '), in Axiom 4 is unique for each  $u$  in  $V$ .

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- For each  $u$  in  $V$  and scalar  $\alpha$  we have

$$0u = 0 \quad \alpha 0 = 0; \quad -u = (-1)u.$$

**Example:** Let  $V$  be the set of all arrows (directed line segments) in three-dimensional space, with two arrows regarded as equal if they have the same length and point in the same direction. Define addition by the parallelogram rule, and for each  $v$  in  $V$ , define  $cv$  to be the arrow whose length is  $c$  times the length of  $v$ , pointing in the same direction as  $v$  if  $c > 0$  and otherwise pointing in the opposite direction.

**Note:** The definition of  $V$  is geometric, using concepts of length and direction. No  $xyz$ -coordinate system is involved. An arrow of zero length is a single point and represents the zero vector. The negative of  $v$  is  $(-1)v$ .

- All axioms are verified

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## More examples

- Set of vectors in  $\mathbb{R}^4$  with second component equal to zero.
- Set of all polynomials of degree  $\leq 3$
- Set of all  $m \times n$  matrices
- Set of all  $n \times n$  upper triangular matrices

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## Subspaces

- A subset  $H$  of vectors of  $V$  is a subspace if it is a vector space by itself. Formal definition:

- A subset  $H$  of vectors of  $V$  is a subspace if

1.  $H$  is closed for the addition, which means:

$$x + y \in H \quad \text{for any } x \in H, y \in H$$

2.  $H$  is closed for the scalar multiplication, which means:

$$\alpha x \in H \quad \text{for any } \alpha \in \mathbb{R}, x \in H$$

- Note: If  $H$  is a subspace then (1)  $\mathbf{0}$  belongs to  $H$  and (2) For any  $x \in H$ , the vector  $-x$  belongs to  $H$

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- Every vector space is a subspace (of itself and possibly of other larger spaces).
- The set consisting of only the zero vector of  $V$  is a subspace of  $V$ , called the zero subspace. Notation:  $\{\mathbf{0}\}$ .

**Example:** Polynomials of the form

$$p(t) = \alpha_2 t^2 + \alpha_3 t^3$$

form a subspace of the space of polynomials of degree  $\leq 3$

 Other examples: Examples 3 and 5 (sec. 4.1) from **text**

**Example:** Triangular matrices

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 Example 8 (sec. 4.1) in **text** is important

 Show that the set  $H$  of all vectors in  $\mathbb{R}^3$  of the form  $\{a + b, a - b, b\}$  is a subspace of  $\mathbb{R}^3$ . [Hint: see example 11 from Sec. 4.1 of **text**]

- Recall: the term **linear combination** refers to a sum of scalar multiples of vectors, and  $\text{span}\{v_1, \dots, v_p\}$  denotes the set of all vectors that can be written as linear combinations of  $v_1, \dots, v_p$ .

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## A subspace spanned by a set

**Theorem:** If  $v_1, \dots, v_p$  are in a vector space  $V$ , then

$$\text{span}\{v_1, \dots, v_p\}$$

is a subspace of  $V$ .

➤  $\text{span}\{v_1, \dots, v_p\}$  is the subspace spanned (or generated) by  $\{v_1, \dots, v_p\}$ .

➤ Given any subspace  $H$  of  $V$ , a spanning (or generating) set for  $H$  is a set  $\{v_1, \dots, v_p\}$  in  $H$  such that  $H = \text{span}\{v_1, \dots, v_p\}$ .

☞ Prove above theorem for  $p = 2$ , i.e., given  $v_1$  and  $v_2$  in a vector space  $V$ , then  $H = \text{span}\{v_1, v_2\}$  is a subspace of  $V$ . [Hint: show that  $H$  is closed for '+' and for scalar multiplication]

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## NULL SPACES AND COLUMN SPACES [4.2]

## Null space of a matrix

**Definition:** The null space of an  $m \times n$  matrix  $A$ , written as  $\text{Nul}(A)$ , is the set of all solutions of the homogeneous equation  $Ax = 0$ . In set notation,

$$\text{Nul}(A) = \{x : x \in \mathbb{R}^n \text{ and } Ax = 0\}.$$

**Theorem:** The null space of an  $m \times n$  matrix  $A$  is a subspace of  $\mathbb{R}^n$

➤ Equivalently, the set of all solutions to a system  $Ax = 0$  of  $m$  homogeneous linear equations in  $n$  unknowns is a subspace of  $\mathbb{R}^n$

**Proof:**  $\text{Nul}(A)$  is by definition a subset of  $\mathbb{R}^n$ . Must show:  $\text{Nul}(A)$  closed under + and multipl. by scalars.

➤ Take  $u$  and  $v$  any two vectors in  $\text{Nul}(A)$ . Then  $Au = 0$  and  $Av = 0$ .

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➤ Need to show that  $u + v$  is in  $\text{Nul}(A)$ , i.e., that  $A(u + v) = 0$ . Using a property of matrix multiplication, compute

$$A(u + v) = Au + Av = 0 + 0 = 0$$

➤ Thus  $u + v \in \text{Nul}(A)$ , and  $\text{Nul}(A)$  is closed under vector addition.

➤ Finally, if  $\alpha$  is any scalar, then  $A(\alpha u) = \alpha(Au) = \alpha(0) = 0$  which shows that  $\alpha u$  is in  $\text{Nul}(A)$ .

➤ Thus  $\text{Nul}(A)$  is a subspace of  $\mathbb{R}^n$ . ■

☞ See Example 1 in Sect. 4.2 of [text](#) [determining if a given vector belongs to  $\text{Nul}(A)$ ]

☞ See Example 2 in Sect. 4.2 of [text](#) [determining a subspace by casting as a null space]

➤ Next we will see how to determine  $\text{Nul}(A)$ . See Example 3 of Sec. 4.2 of [text](#). Details next.

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- There is no obvious relation between vectors in  $\text{Nul}(A)$  and the entries in  $A$ .
- We say that  $\text{Nul}(A)$  is defined **implicitly**, because it is defined by a condition that must be checked.
- No explicit list or description of the elements in  $\text{Nul}(A)$ , so..
- ... we need to solve the equation  $Ax = 0$  to produce an explicit description of  $\text{Nul}(A)$ .

**Example:** Find the null space of the matrix

$$A = \begin{bmatrix} -3 & 6 & -1 & 1 & -7 \\ 1 & -2 & 2 & 3 & -1 \\ 2 & -4 & 5 & 8 & -4 \end{bmatrix}$$

- We will find a **spanning set** for  $\text{Nul}(A)$ .

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**Solution:** first step is to find the general solution of  $Ax = 0$  in terms of free variables. We know how to do this.

- Get reduced echelon form of augmented matrix  $[A \ 0]$ :

$$\begin{bmatrix} 1 & -2 & 0 & -1 & 3 & 0 \\ 0 & 0 & 1 & 2 & -2 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix} \rightarrow \begin{array}{l} x_1 - 2x_2 - x_4 + 3x_5 = 0 \\ x_3 + 2x_4 - 2x_5 = 0 \\ 0 = 0 \end{array}$$

- $x_2, x_4, x_5$  are free variables,  $x_1, x_3$  basic variables.
- For any selection of the free variables, can find a vector in  $\text{Nul}(A)$  by computing  $x_1, x_3$  in terms of these variables:

$$\begin{aligned} x_1 &= 2x_2 + x_4 - 3x_5 \\ x_3 &= -2x_4 + 2x_5 \end{aligned}$$

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- OK - but how can we write these using spanning vectors (i.e. as linear combinations of specific vectors?)
- Solution - write  $x$  as:

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} = \begin{bmatrix} 2x_2 + x_4 - 3x_5 \\ x_2 \\ -2x_4 + 2x_5 \\ x_4 \\ x_5 \end{bmatrix} = x_2 \underbrace{\begin{bmatrix} 2 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}}_u + x_4 \underbrace{\begin{bmatrix} 1 \\ 0 \\ -2 \\ 1 \\ 0 \end{bmatrix}}_v + x_5 \underbrace{\begin{bmatrix} -3 \\ 0 \\ 2 \\ 0 \\ 1 \end{bmatrix}}_w$$

- General solution is of the form  $x_2u + x_4v + x_5w$ .
- Every linear combination of  $u, v$ , and  $w$  is an element of  $\text{Nul}(A)$ . Thus  $\{u, v, w\}$  is a spanning set for  $\text{Nul}(A)$ , i.e.,

$$\text{Nul}(A) = \text{span}\{u, v, w\}$$

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☞ Obtain the vector  $x$  of  $\text{Nul}(A)$  corresponding to the choice:  $x_2 = 1, x_4 = -2, x_5 = -1$ . Verify that indeed it is in the null space, i.e., that  $Ax = 0$

☞ For same example, find a vector in  $\text{Nul}(A)$  whose last two components are zero and whose first component is 1. How many such vectors are there (zero, one, or infinitely many?)

**Notes:**

- 1. The spanning set produced by the method in the example is guaranteed to be linearly independent
- ☞ Show this (proof by contradiction)
- 2. When  $\text{Nul}(A)$  contains nonzero vectors, the number of vectors in the spanning set for  $\text{Nul}(A)$  equals the number of free variables in the equation  $Ax = 0$ .

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## Column Space of a matrix

**Definition:** The column space of an  $m \times n$  matrix  $A$ , written as  $\text{Col}(A)$  (or  $C(A)$ ), is the set of all linear combinations of the columns of  $A$ . If  $A = [a_1 \cdots a_n]$ , then

$$\text{Col}(A) = \text{span}\{a_1, \dots, a_n\}$$

**Theorem:** The column space of an  $m \times n$  matrix  $A$  is a subspace of  $\mathbb{R}^m$ .

► A vector in  $\text{Col}(A)$  can be written as  $Ax$  for some  $x$  [Recall that  $Ax$  stands for a linear combination of the columns of  $A$ ].

That is:  $\text{Col}(A) = \{b : b = Ax \text{ for some } x \text{ in } \mathbb{R}^n\}$

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► The notation  $Ax$  for vectors in  $\text{Col}(A)$  also shows that  $\text{Col}(A)$  is the range of the linear transformation  $x \rightarrow Ax$ .

► The column space of an  $m \times n$  matrix  $A$  is all of  $\mathbb{R}^m$  if and only if the equation  $Ax = b$  has a solution for each  $b$  in  $\mathbb{R}^m$

Let

$$A = \begin{bmatrix} 2 & 4 & -2 & 1 \\ -2 & -5 & 7 & 3 \\ 3 & 7 & -8 & 6 \end{bmatrix}, \quad u = \begin{bmatrix} 3 \\ -2 \\ -1 \\ 0 \end{bmatrix}, \quad v = \begin{bmatrix} 3 \\ -1 \\ 3 \end{bmatrix}$$

a. Determine if  $u$  is in  $\text{Nul}(A)$ . Could  $u$  be in  $\text{Col}(A)$ ?

b. Determine if  $v$  is in  $\text{Col}(A)$ . Could  $v$  be in  $\text{Nul}(A)$ ?

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► General remarks and hints:

1.  $\text{Col}(A)$  is a subspace of  $\mathbb{R}^m$  [ $m = 3$  in above example]
2.  $\text{Nul}(A)$  is a subspace of  $\mathbb{R}^n$  [ $n = 4$  in above example]
3. To verify that a given vector  $x$  belongs to  $\text{Nul}(A)$  all you need to do is check if  $Ax = 0$
4. To verify if  $b \in \text{Col}(A)$  all you need to do is check if the linear system  $Ax = b$  has a solution.

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