2 Use the min-max theorem to show that  $||A||_2 = \sigma_1(A)$  - the largest singular value of A.

**Solution:** This comes from the fact that:

$$egin{aligned} |A\|_2^2 &= \max_{x 
eq 0} rac{\|Ax\|_2^2}{\|x\|_2^2} \ &= \max_{x 
eq 0} rac{(Ax,Ax)}{(x,x)} \ &= \max_{x 
eq 0} rac{(A^TAx,A)}{(x,x)} \ &= \lambda_{max}(A^TA) \ &= \sigma_1^2 \end{aligned}$$

Suppose that  $A = LDL^T$  where L is unit lower triangular, and D diagonal. How many negative eigenvalues does A have?

Solution: It has as many negative eigenvalues as there are negative entries in D

Assume that A is tridiagonal. How many operations are required to determine the number of negative eigenvalues of A?

Solution: The rough answer is O(n) – because an LU (and therefore LDLT) factorization costs O(n). Based on doing the LU factorization of a triagonal matrix, a more accurate answer is 3n operations.

 $\checkmark$  Devise an algorithm based on the inertia theorem to compute the *i*-th eigenvalue of a tridiagonal matrix.

**Solution:** Here is a matlab script:

```
function [sigma] = bisect(d, b, i, tol)
%% function [sigma] = bisect(d, b, i, tol)
%% d = diagonal of T
%% b = co-diagonal
%% i = compute i-th eigenvalue
%% tol = tolerance used for stopping
    b(1) = 0;
    n = length(d);
%%------ guershgorin
```

```
tmin = d(n) - abs(b(n));
tmax = d(n) + abs(b(n));
for j=1:n-1
  rho = abs(b(j)) + abs(b(j+1));
  tmin = min(tmin, d(j)-rho);
  tmax = max(tmax, d(j)+rho);
end
tol = tol*(tmax-tmin);
for iter=1:100
  sigma = 0.5*(tmin+tmax);
  count = sturm(d, b, sigma);
  if (count >= i)
    tmin = sigma;
  else
    tmax = sigma;
  end
  if (tmax - tmin) < tol
    break
  end
end
```

 $\swarrow_{6}$  What is the inertia of the matrix

$$egin{pmatrix} I & F \ F^T & 0 \end{pmatrix}$$

where F is  $m \times n$ , with n < m, and of full rank?

[Hint: use a block LU factorization]

**Solution:** We start with

$$\begin{pmatrix} I & F \\ F^T & 0 \end{pmatrix} = \begin{pmatrix} I & 0 \\ F^T & I \end{pmatrix} \begin{pmatrix} I & F \\ 0 & -F^T F \end{pmatrix}$$
$$= \begin{pmatrix} I & 0 \\ F^T & I \end{pmatrix} \begin{pmatrix} I & 0 \\ 0 & -F^T F \end{pmatrix} \begin{pmatrix} I & F \\ 0 & I \end{pmatrix}$$
$$= \begin{pmatrix} I & 0 \\ F^T & I \end{pmatrix} \begin{pmatrix} I & 0 \\ 0 & -F^T F \end{pmatrix} \begin{pmatrix} I & 0 \\ F^T & I \end{pmatrix}^T$$

This is of the form  $XDX^T$  where X is invertible. Therefore the inertia is the same as that of the block diagonal matrix which is: m positive eigenvalues (block I) and n negative eigenvalues since  $-F^TF$  is  $n \times n$  and negative definite.

 $\swarrow_7$  Let  $\|A_O\|_I = \max_{i \neq j} |a_{ij}|$ . Show that

$$\|A_O\|_F \leq \sqrt{n(n-1)} \|A_O\|_I$$

**Solution:** This is straightforward:

$$\|A_O\|_F^2 = \sum_{i 
eq j} |a_{ij}|^2 \le n(n-1) \max_{i 
eq j} |a_{ij}|^2 = n(n-1) \|A_O\|_I^2.$$

 $\swarrow_{8}$  Use this to show convergence in the case when largest entry is zeroed at each step.

**Solution:** If we call  $B_k$  the matrix  $A_O$  after each rotation then we have according to result in the previous page and using the previous exercise:

$$egin{aligned} B_{k+1} \|_F^2 &= \|B_k\|_F^2 - 2a_{pq}^2 \ &= \|B_k\|_F^2 - 2\|B_k\|_I^2 \ &\leq \|B_k\|_F^2 - rac{2}{n(n+1)}\|B_k\|_F^2 \ &= \left[1 - rac{2}{n(n+1)}
ight] \, \|B_k\|_F^2 \end{aligned}$$

which shows that the norm will be decreasing by factor less than a constant that is less than one

- therefore it converges to zero.