

The Kernel (and Process) Abstraction

Chapter 2-3 OSPP

Part I

Announcements

- Today: kernel
 - Asynchrony
 - Processes
 - Protection

Kernel

- The software component that controls the hardware directly and implements the core privileged OS functions.
- Modern hardware has features that allow the OS kernel to protect itself from untrusted user code.

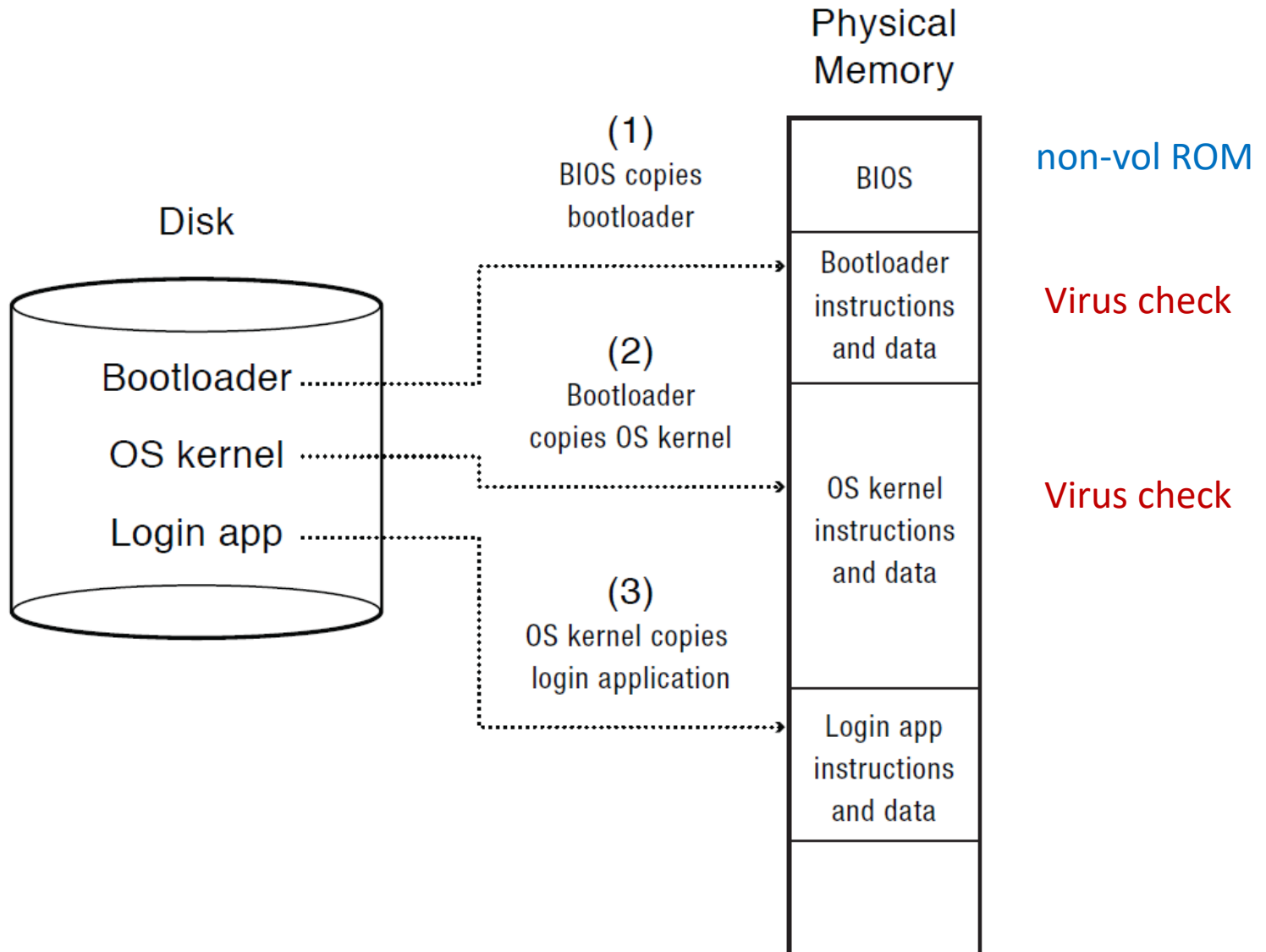
Kernel Protection

- Reliability
 - crashes
- Security
 - Write to arbitrary disk (or memory) locations
- Privacy
 - User files

Does kernel/OS teach any lessons I can use?

- Yes!
- Protection
 - Trend is for apps to be mini-OS?
 - Browser
- Resource management
 - Trend is to give apps X resources and let them figure out how to share
 - User threads, virtual machines
- Asynchrony and many others

A Short Digression: Starting the Kernel: Booting



Challenge: Asynchrony: Device Interrupts

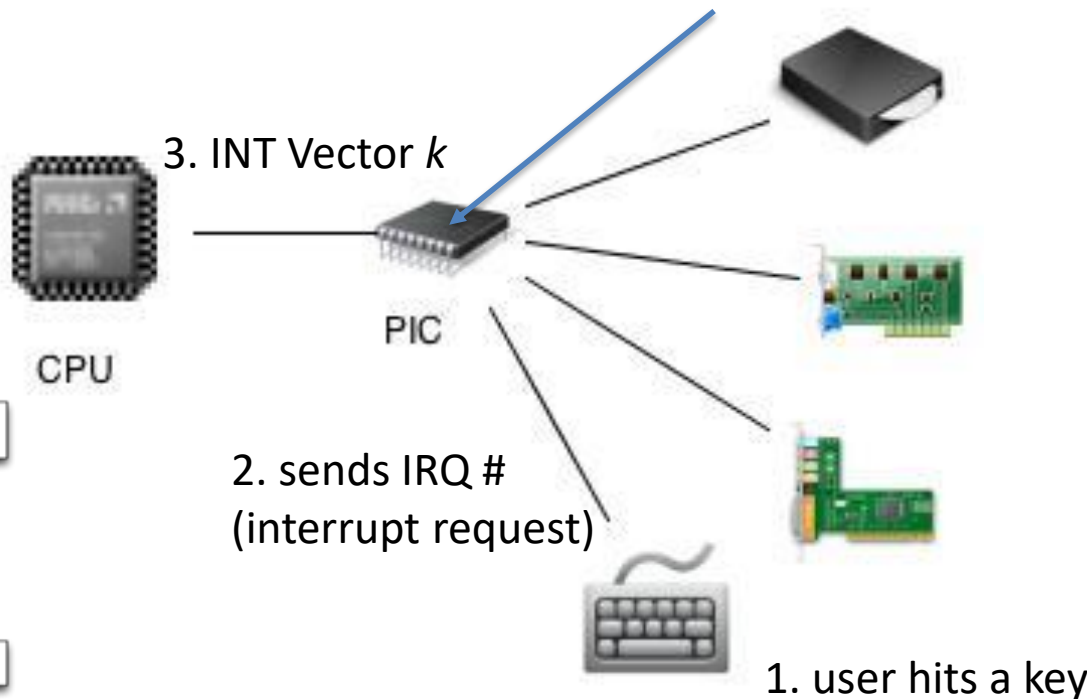
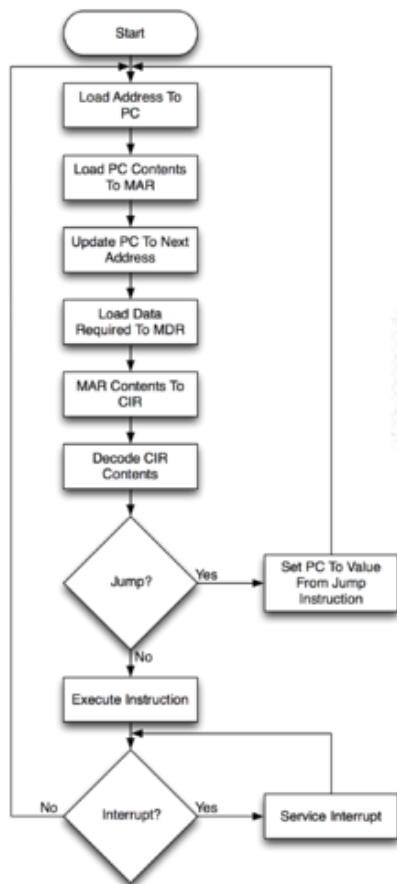
- OS kernel needs to communicate with physical devices
- Devices operate asynchronously from the CPU
 - Polling: Kernel waits until I/O is done
 - Interrupts: Kernel can do other work in the meantime
- Device access to memory
 - Programmed I/O: CPU reads and writes to device
 - Direct memory access (DMA) by device

Device Interrupts

- How do device interrupts work?
 - Where does the CPU run after an interrupt?
 - What is the interrupt handler written in? C? Java?
 - What stack does it use?
 - Is the work the CPU had been doing before the interrupt lost forever?
 - If not, how does the CPU know how to resume that work?
 - Will come back to this soon

How it all happens

programmable interrupt controller (x86)



CPU checks for interrupts after each instruction cycle
oops, looks like we are “polling” after all but in h/w 😊

Device Driver and I/O Interrupts

- Top half of driver called from syscall handler
 - issues privileged instructions: read from disk, done
- Bottom half
 - called when interrupt arrives
 - interrupt handling: I/O completion or error recovery

Interrupt Handler

- Bottom half
 - runs first called directly by hardware, saves state of hardware, then enables top half to run
- Top half ~ interrupt handler specifics
 - for an I/O event: calls driver bottom half: e.g. data copying

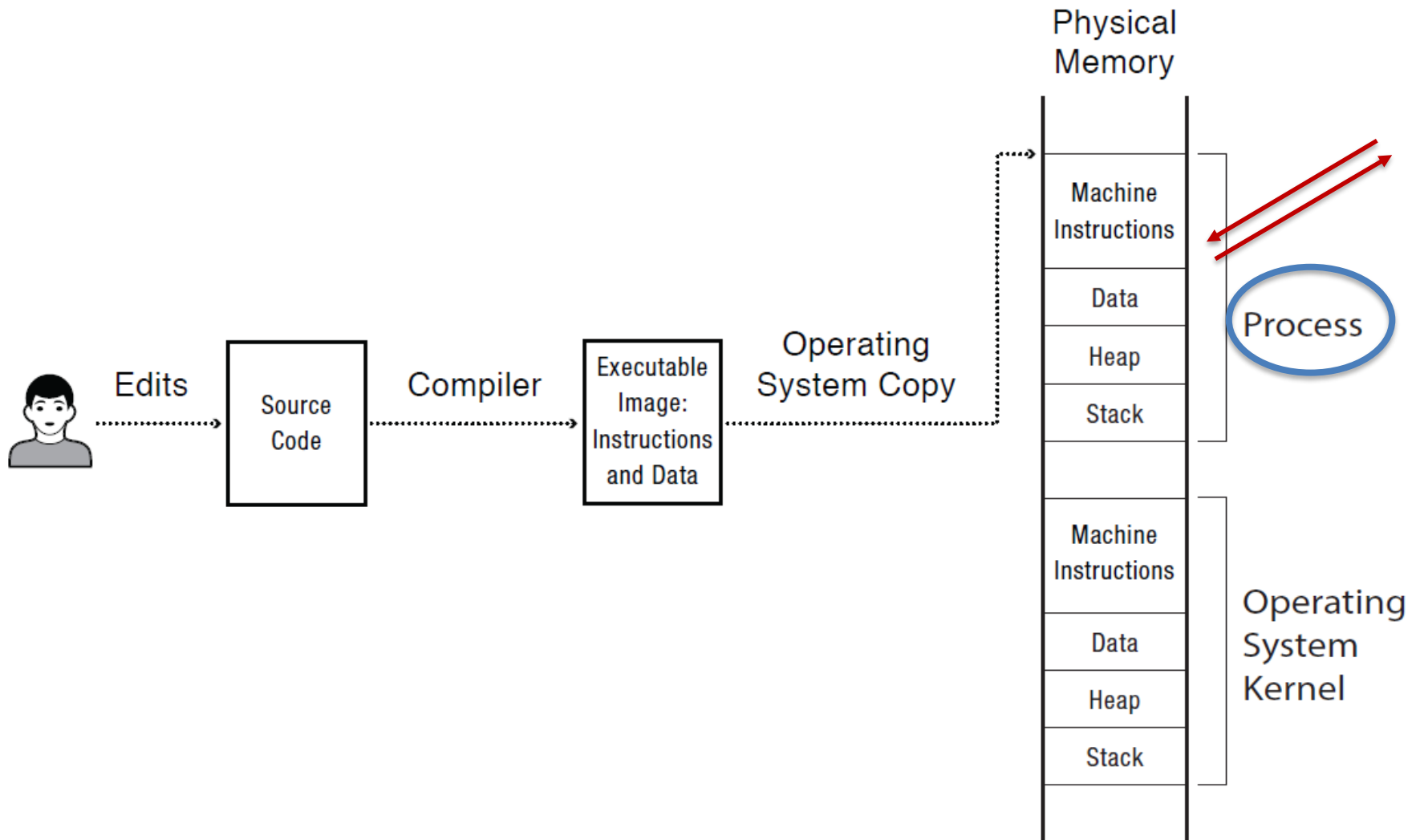
Buggy Device Drivers

- Validate/inspect
- User-level drivers
- Running drivers in VM
- Sandboxing
 - mini-execution environment in the kernel

Challenge: Protection

- How do we execute code with restricted privileges?
 - Either because the code is buggy or if it might be malicious
- Some examples:
 - A script running in a web browser
 - A program you just downloaded off the Internet
 - A program you just wrote that you haven't tested yet
 - First see how OS does it

A Problem: both constrain and protect process



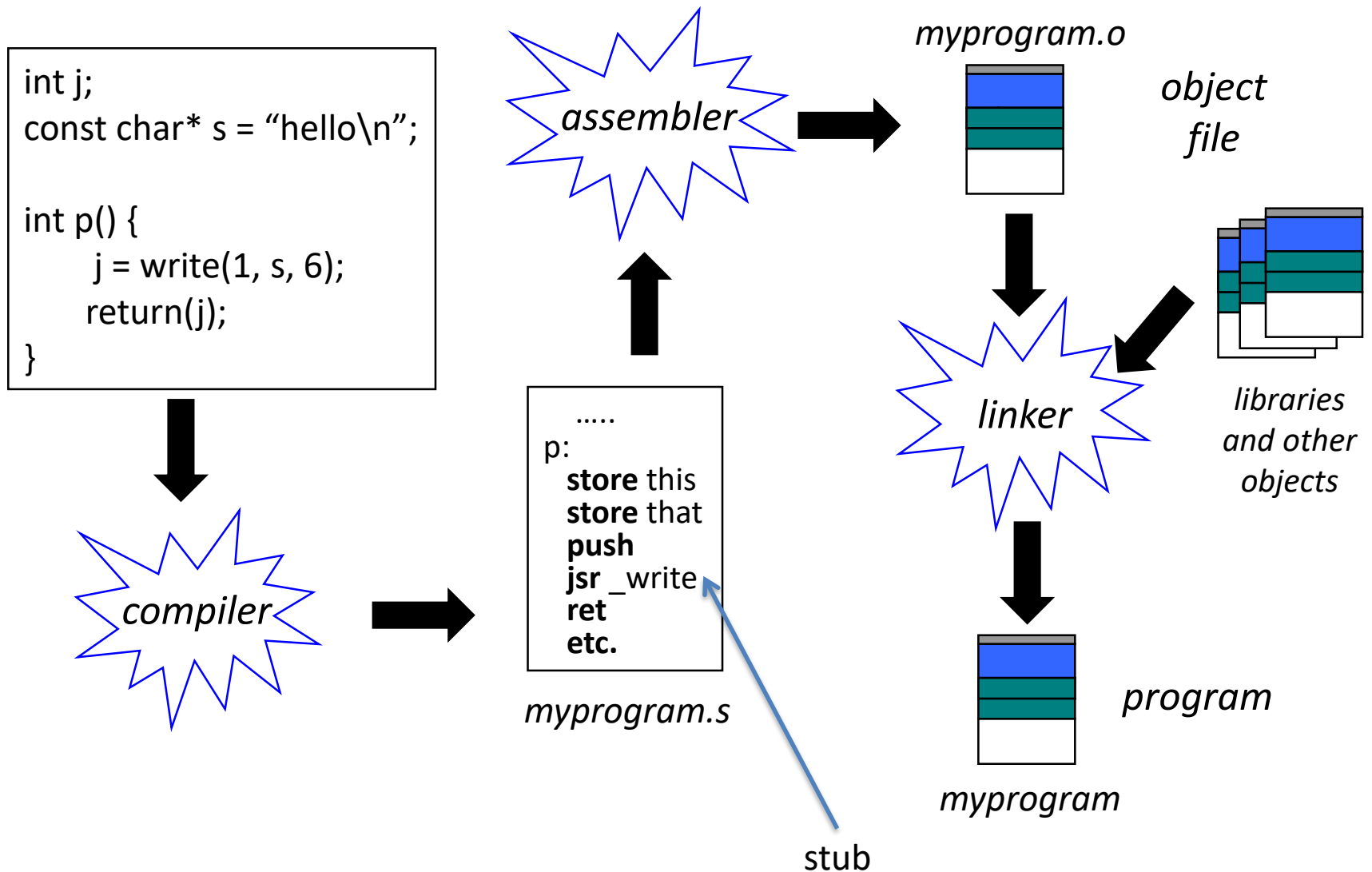
Main Points

- Process concept
 - A process is the OS abstraction for executing a program with **limited** privileges but that is **isolated**
- Dual-mode operation: user vs. kernel
 - Kernel-mode: execute with complete privileges
 - User-mode: execute with fewer privileges
 - Processor is a warden (OS) and an inmate (process)!
- Safe control transfer
 - How do we switch from one mode to the other?

Process Abstraction

- Process: an *instance* of a program, running with limited rights
 - Thread: a sequence of instructions within a process
 - Potentially many threads per process (for now 1:1)
 - Address space: set of rights of a process
 - Memory that the process can access
 - Other permissions the process has (e.g., which system calls it can make, what files it can access)

The Birth of a Program



Birth of a Process: Process State

Stored in **PCB** (Process Control Block)

Information associated with each process

- Program counter, stack pointer
- CPU registers
- CPU scheduling information
- Memory-management information
- Accounting information
- I/O status information
- Open files, signals (if UNIX)

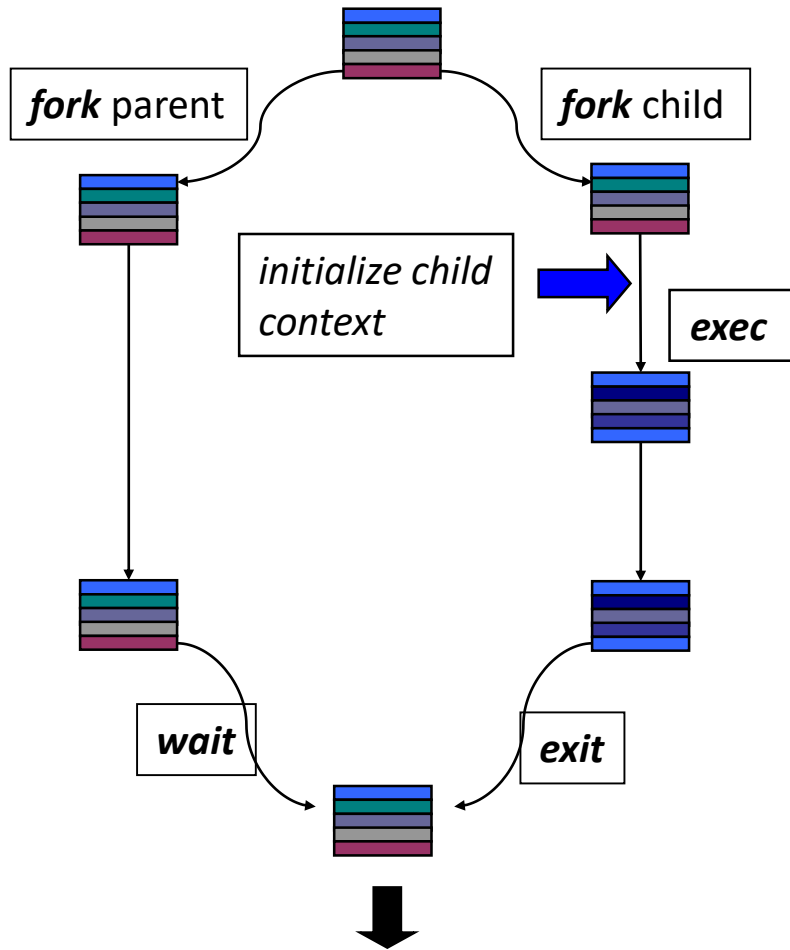
Process API

- Very briefly

UNIX Process Management

- UNIX fork – system call to create a copy of the current process, and start it running
 - No arguments!
- UNIX exec – system call to change the program being run by the current process
- UNIX wait – system call to wait for a process to finish
- UNIX signal – system call to send a notification to another process
- UNIX/LINUX clone – similar to fork but used with threads

Unix Fork/Exec/Exit/Wait Example



```
int pid = fork();
```

Create a new process that is a clone of its parent.

```
exec*("program" [, argv, envp]);
```

Overlay the calling process virtual memory with a new program, and transfer control to it.

```
exit(status);
```

Exit with status, destroying the process.

```
int pid = wait*(&status);
```

Wait for exit (or other status change) of a child.

Corner cases: orphans and zombies

Example: Process Creation in Unix

```
int pid;  
int status = 0;  
  
if (pid = fork()) {  
    /* parent */  
    ....  
    pid = wait(&status);  
} else {  
    /* child */  
    ....  
    exit(status);  
}
```

The **fork** syscall returns twice: it returns a zero to the child and the child process ID (pid) to the parent.

Parent uses **wait** to sleep until the child exits; **wait** returns child pid and status.

Implementing UNIX fork

Steps to implement UNIX fork

- Create and initialize the process control block (PCB) in the kernel
- Create a new address space
- Initialize the address space with a copy of the entire contents of the address space of the parent
 - mostly sets up the page table
 - some implementations share portions of address space initially (copy-on-write)
- Inherit parent execution context (e.g., any open files, PC, SP)
- Inform the scheduler that the new process is ready to run

Implementing UNIX exec

- Steps to implement UNIX exec
 - Load the program into the current address space
 - Copy arguments into memory in the address space
 - Initialize the hardware context to start execution at ``start'' (reset PC)

Questions

- Can UNIX `fork()` return an error? Why?
- Can UNIX `exec()` return an error? Why?
- Can UNIX `wait()` ever return immediately? Why?

Starting a New Process

- Allocate PCB; in Unix this is already done by `fork`
- Allocate memory (as needed, on demand)
 - “Copy” program from disk into memory
 - Allocate user stack
 - Allocate heap
- Allocate kernel stack (sys calls, interrupts, exceptions)

Starting a New Process (cont'd)

- Transfer to user mode
- If Exec path (vs. fork)
 - Copy arguments into user memory (e.g. `argc`, `argv`)
 - Jump to `start` address

```
start (arg1, arg2) {  
    main (arg1, arg2);  
    exit ();  
}
```

Why not just call main?

Back to Protection

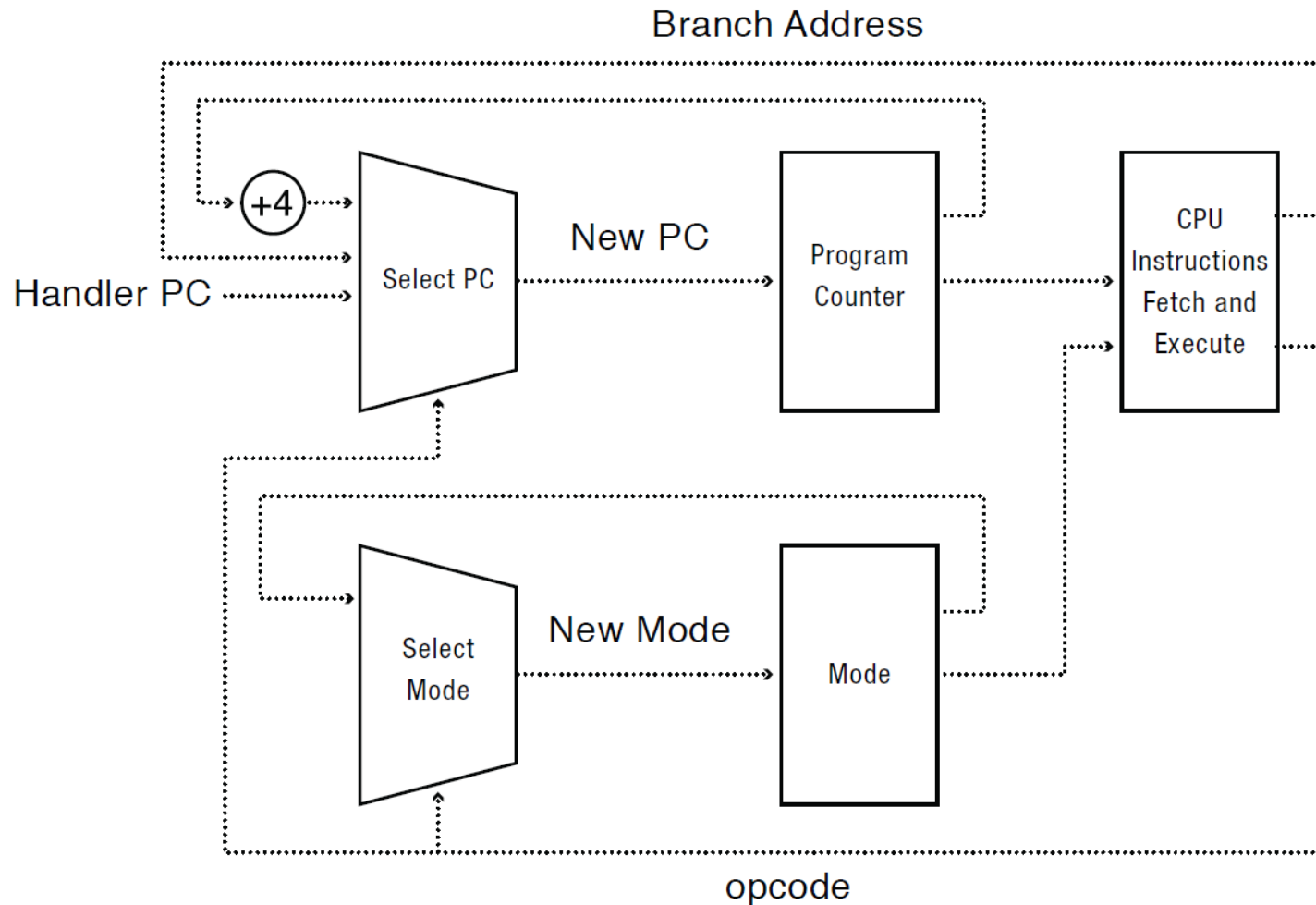
Thought Experiment

- How can we implement execution with limited privilege (no hardware support)?
- How do we go faster?

Hardware Support: Dual-Mode Operation

- Kernel mode
 - Execution with the full privileges of the hardware
 - Read/write to any memory, access any I/O device, read/write any disk sector, send/read any packet
- User mode
 - Limited privileges
 - Only those granted by the operating system kernel
- On the x86, mode stored in EFLAGS register
- On the MIPS, mode in the status register

A CPU with Dual-Mode Operation



Where do interrupts fit in?

The Kernel Abstraction

Chapter 2 OSPP

Part II

Hardware Support: Dual-Mode Operation

- Privileged instructions
 - Available to kernel
 - Not available to user code
- Limits on memory accesses
 - To prevent user code from overwriting the kernel
- Timer
 - To regain control from a user program in a loop
- Safe way to switch from user mode to kernel mode, and vice versa

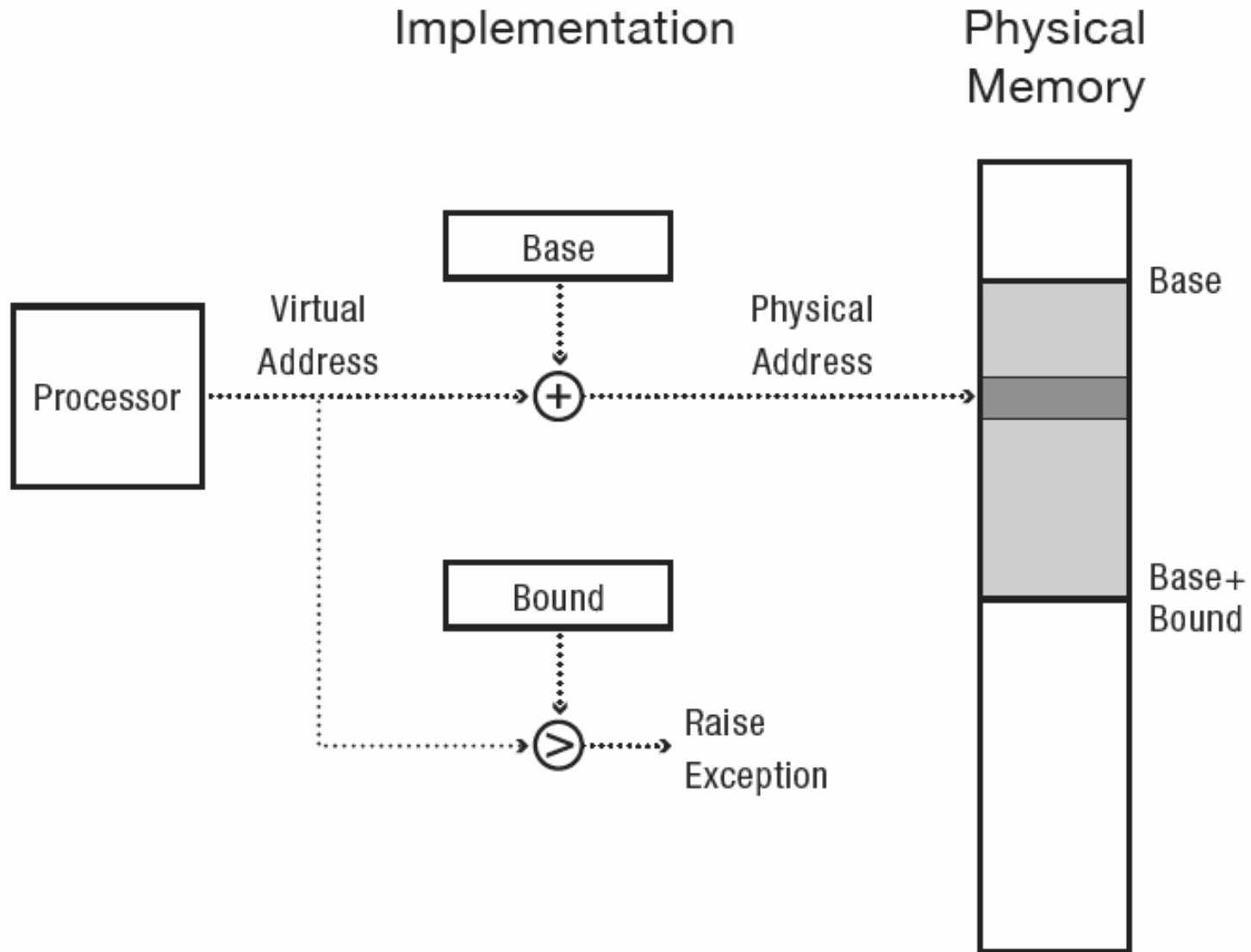
Privileged instructions

- Examples?
- What should happen if a user program attempts to execute a privileged instruction?

Question

- For a “Hello world” program, the kernel must copy the string from the user program memory into the screen memory.
- Why not allow the application to write directly to the screen’s buffer memory?

Simple Memory Protection



Towards Virtual Addresses

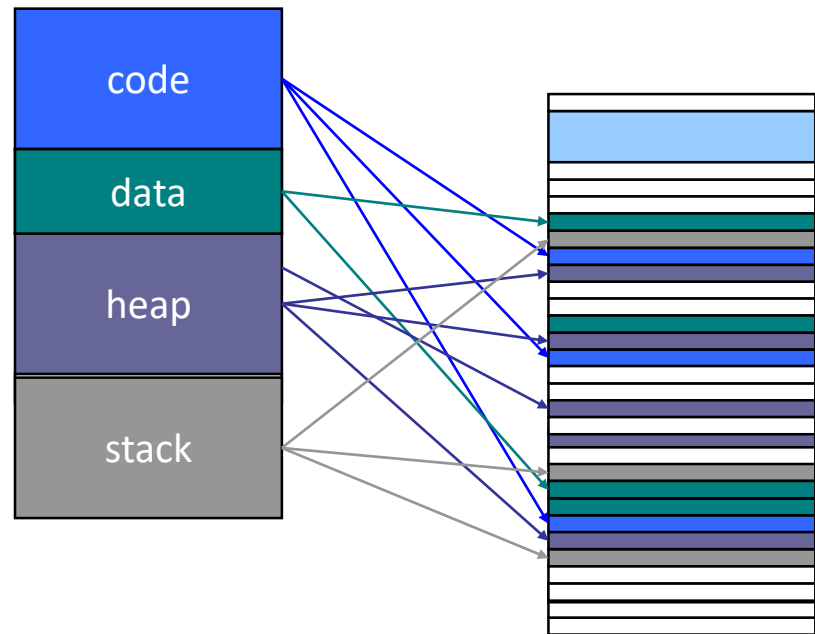
- Problems with base and bound?

Virtual Addresses

- Translation done in hardware, using a table
- Table set up by operating system kernel

Virtual Address space

Physical memory



Example

```
int staticVar = 0;           // a static variable
main() {
    int local_var;
    staticVar += 1;
    sleep(10); // sleep for x seconds
    printf ("static address: %p, local: %p\n",
            &staticVar, &localVar);
}
```

What happens if we run two instances of this program at the same time: staticVar, localVar?

Back to Interrupts: Hardware Timer

- Hardware device that periodically interrupts the processor
 - Returns control to the kernel handler
 - Interrupt frequency set by the kernel
 - Not by user code!
 - Interrupts can be temporarily deferred
 - Not by user code!
 - Interrupt deferral crucial for implementing mutual exclusion
 - Important for protection as well as scheduling

Mode Switch

- From user mode to kernel mode
 - Interrupts
 - Triggered by timer and I/O devices
 - Exceptions
 - Triggered by unexpected program behavior
 - Or malicious behavior!
 - System calls (aka protected procedure call)
 - Request by program for kernel to do some operation on its behalf
 - Only limited # of very carefully coded entry points

Simple Examples

- Examples of exceptions
 - Memory error
 - Divide by 0
- Examples of system calls
 - `read/write`

Mode Switch

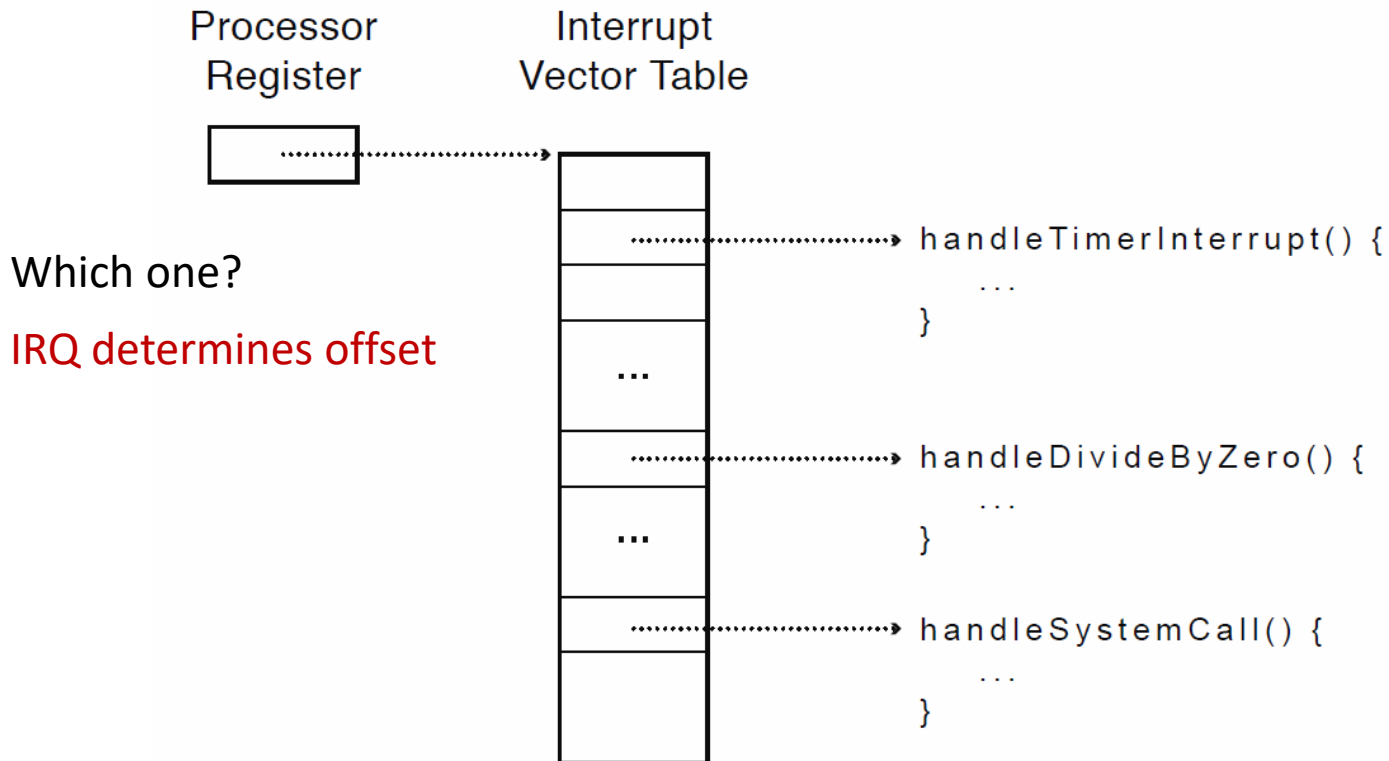
- From kernel mode to user mode
 - New process/new thread start
 - Jump to first instruction in program/thread
 - Return from interrupt, exception, system call
 - Resume suspended execution
 - Process/thread context switch
 - Resume some other process
 - User-level upcall (UNIX signal)
 - Asynchronous notification to user program

How do we handle interrupts safely?

- Interrupt vector
 - Limited number of entry points into kernel
- Atomic transfer of control
 - Single instruction to change (all changed together)
 - Program counter
 - Stack pointer
 - Kernel/user mode
 - Memory protection
- Transparent re-startable execution
 - User program does not know interrupt occurred

Interrupt Vector

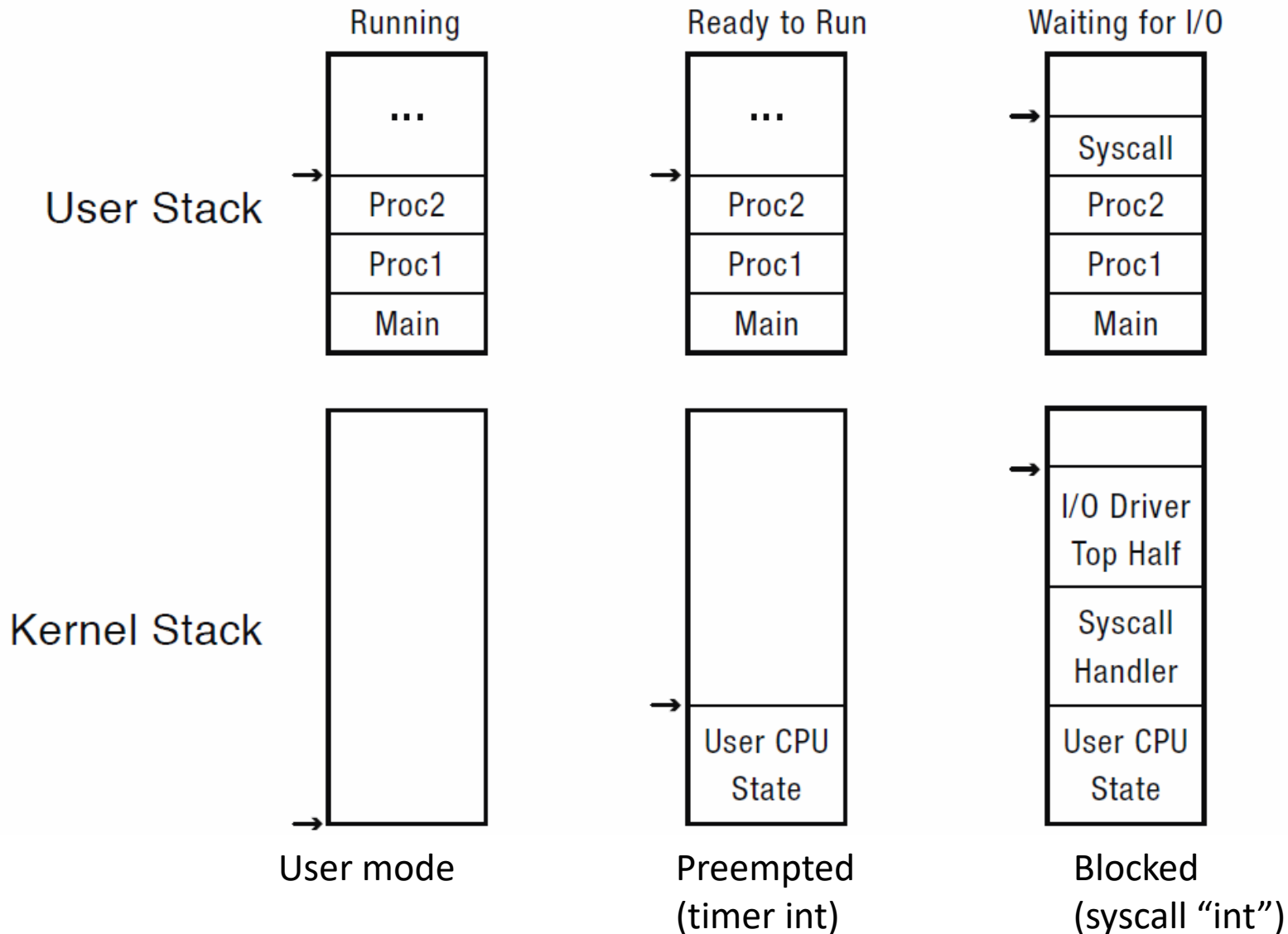
- Table set up by OS kernel; pointers to code to run on different events



Interrupt Stack

- Per-processor, located in kernel (not user) memory
 - Usually a process/thread has both: kernel and user stack
- Why can't the interrupt handler run on the stack of the interrupted user process?
 - user stack may be corrupted or modified

Interrupt Stack



Interrupt Masking

- Interrupt handler runs with interrupts off
 - Why do we need to mask/buffer interrupts in the handler?
 - Re-enabled when interrupt completes
- OS kernel can also turn interrupts off
 - Eg., when determining the next process/thread to run
 - On x86
 - CLI: disable interrupts
 - STI: enable interrupts
 - Only applies to the current CPU core
- We'll need this to implement synchronization in chapter 5

Case Study: x86 Interrupt

- Save current stack pointer
- Save current program counter
- Save current processor status word (condition codes: conditional results, arithmetic carry, ...)
- Switch to kernel stack; put SP, PC, PSW on stack
- **Switch to kernel mode**
- Vector through interrupt table
- Interrupt handler saves registers it might use
 - `pushad`: save 'em all

Before Interrupt

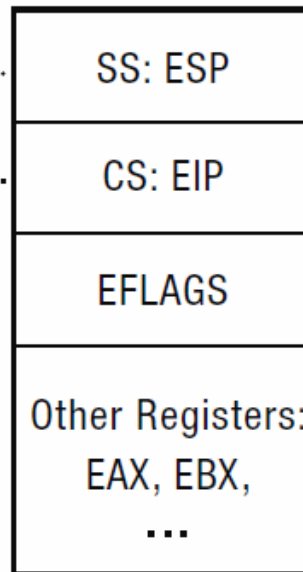
User-level Process

```
foo () {  
  while(...) {  
    x = x+1;  
    y = y-2;  
  }  
}
```

User Stack



Registers

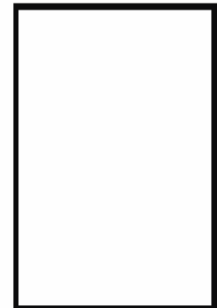


PSW

Kernel

```
handler() {  
  pushad  
  ...  
}
```

Interrupt Stack



Jumped to Interrupt Handler

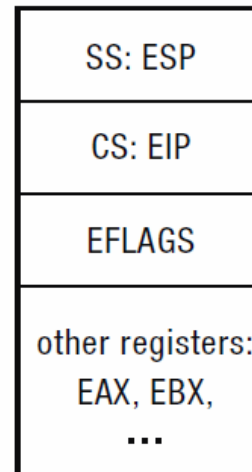
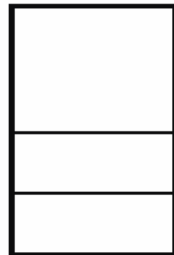
User-level Process

Registers

Kernel

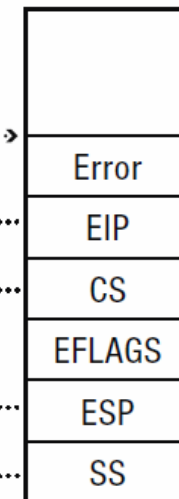
```
foo () {  
    while(...) {  
        x = x+1;  
        y = y-2;  
    }  
}
```

User Stack

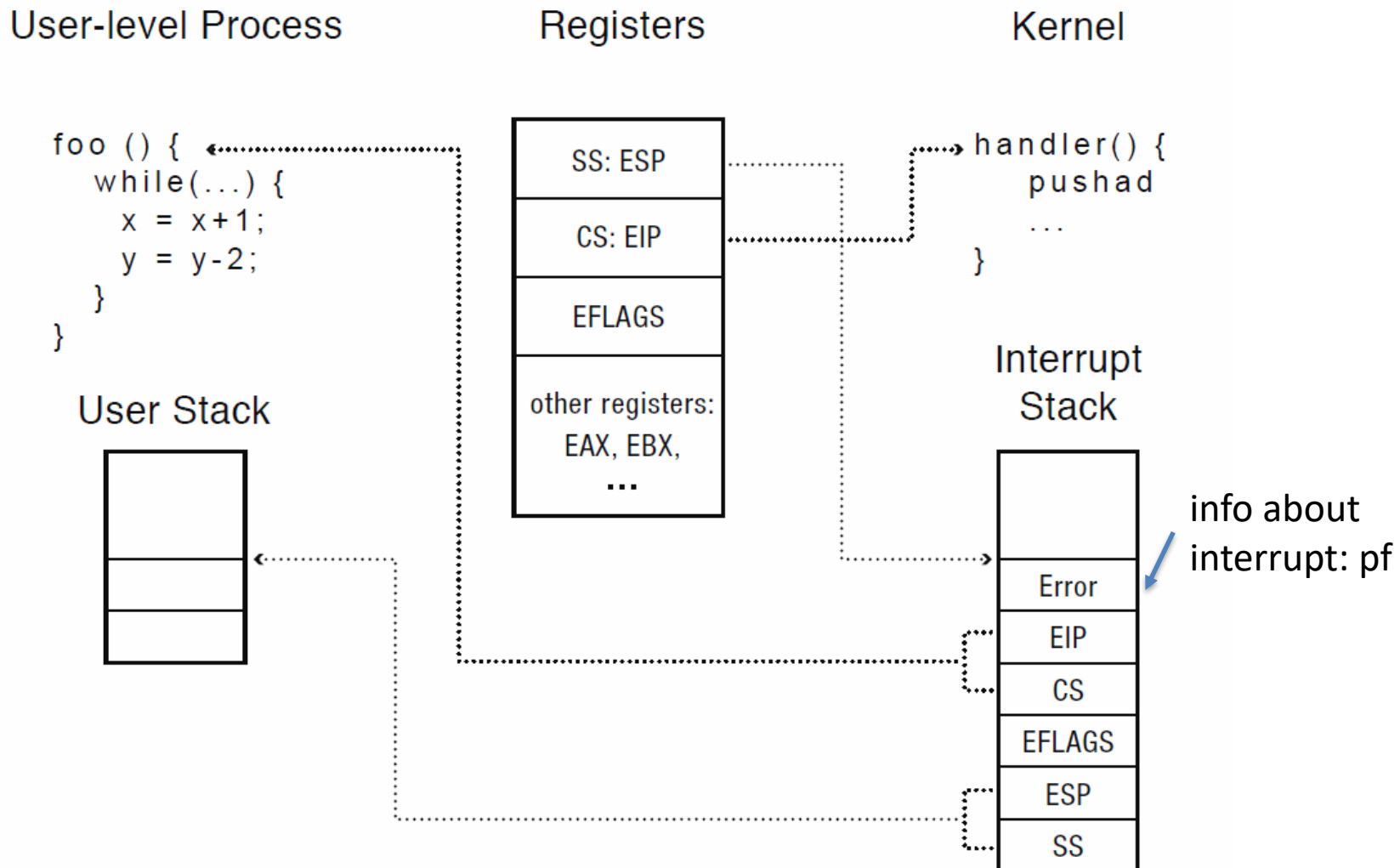


```
handler() {  
    pushad  
    ...  
}
```

Interrupt Stack



info about
interrupt: pf



Executing the handler

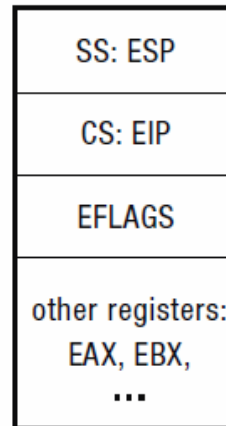
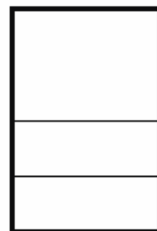
User-level Process

Registers

Kernel

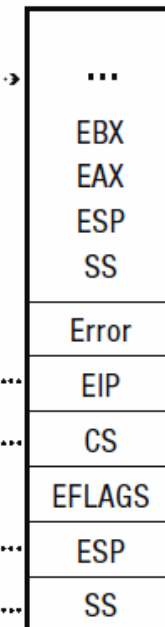
```
foo () {  
  while(...) {  
    x = x+1;  
    y = y-2;  
  }  
}
```

Stack

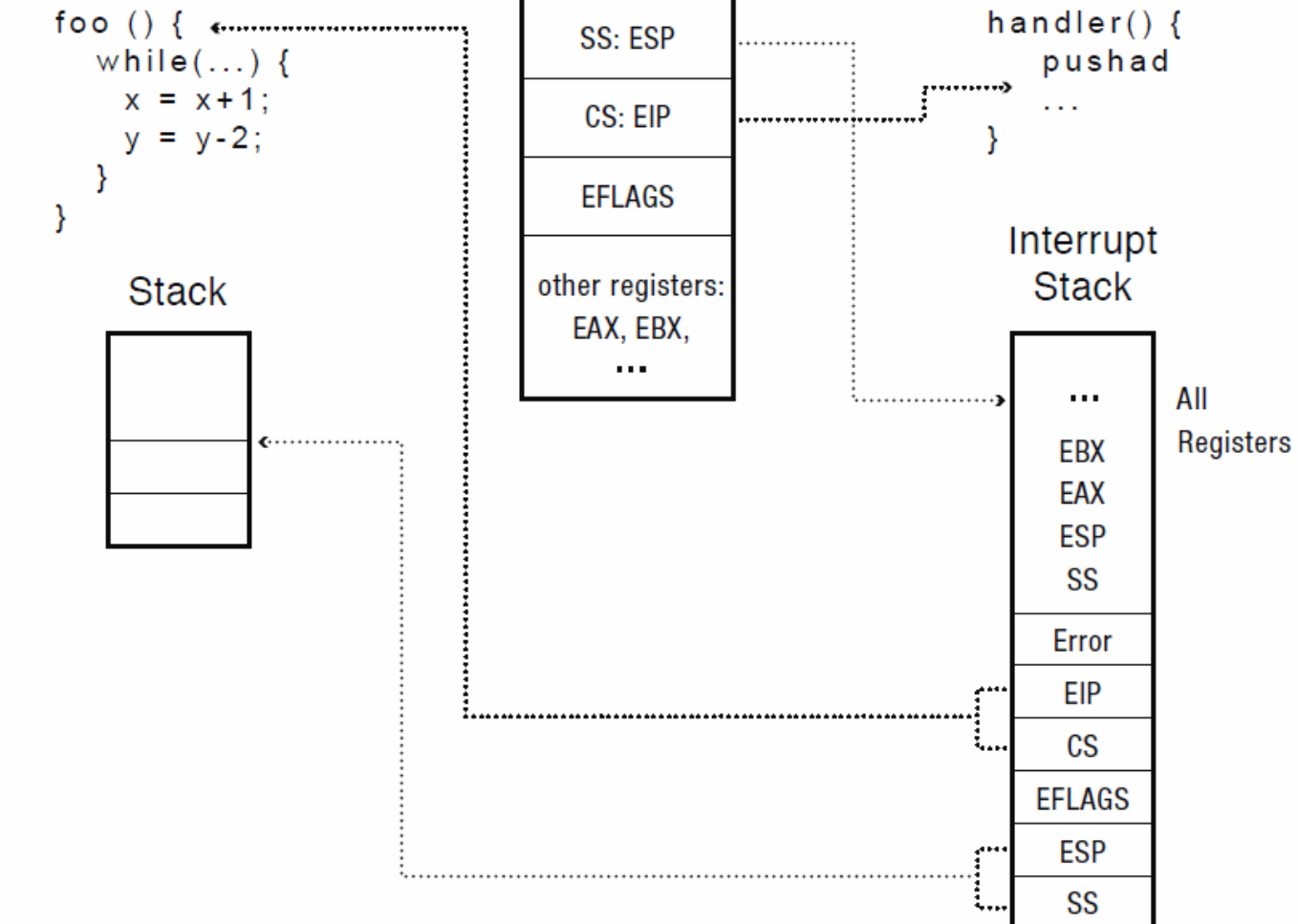


```
handler() {  
  pushad  
  ...  
}
```

Interrupt Stack



All Registers



At end of handler

- Handler restores saved registers
- Atomically returns to interrupted process/thread (hopefully)
 - Restore program counter
 - Restore program stack
 - Restore processor status word
 - **Switch to user mode**

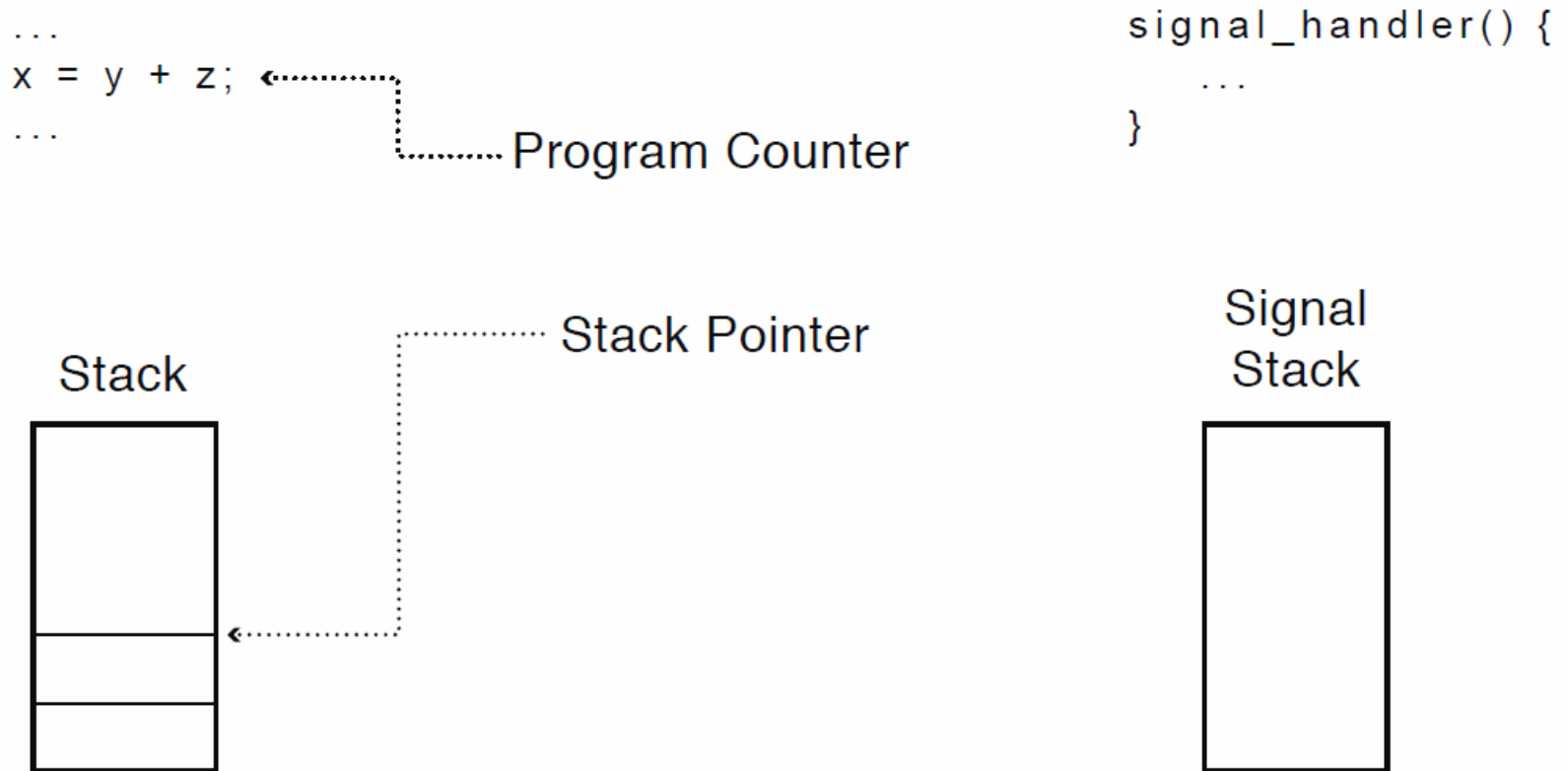
Upcall: User-level event delivery

- Notify user process of some event that needs to be handled right away
 - Time expiration
 - Real-time alarm
 - Time-slice for user-level thread manager
 - Interrupt delivery for VM player
 - Asynchronous I/O completion (`async/await`)
- AKA UNIX signal

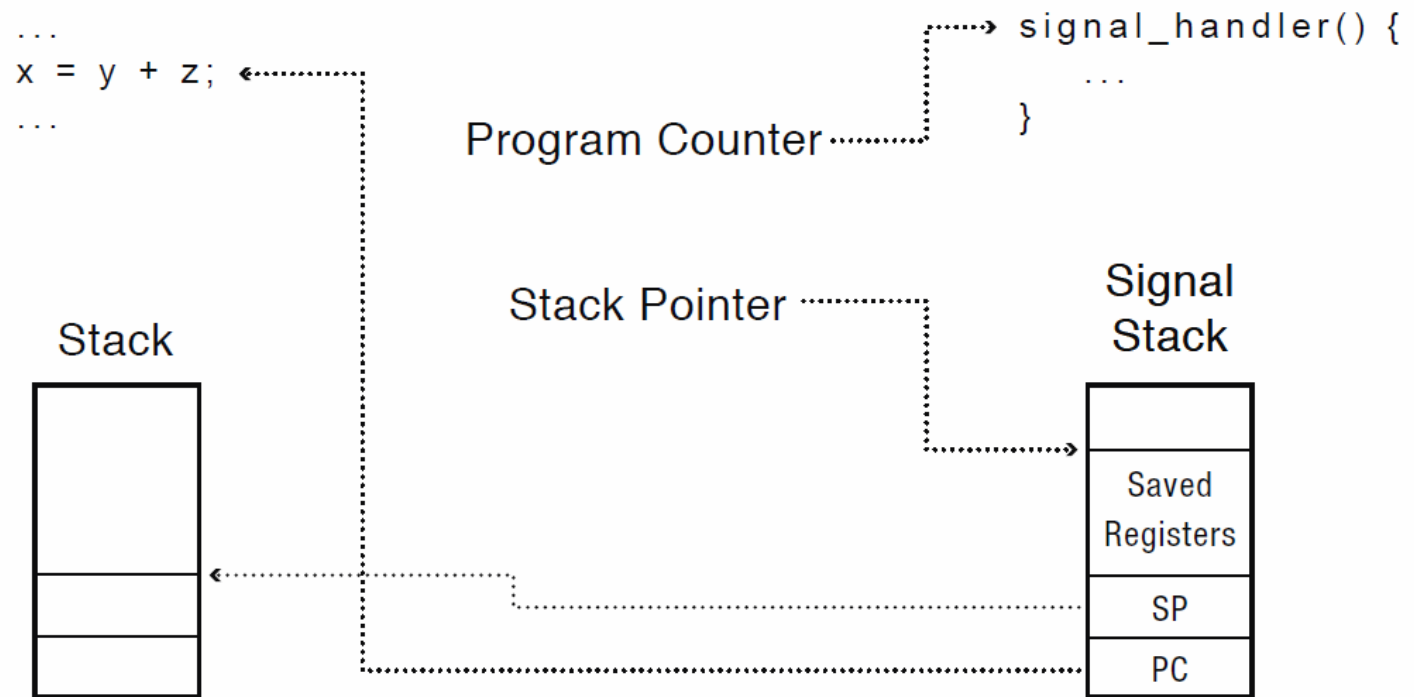
Upcalls vs Interrupts

- Signal handlers ~ interrupt vector
- Signal stack ~ interrupt stack
- Automatic save/restore registers = transparent resume
- Signal masking: signals disabled while in signal handler
- But it runs in user-land

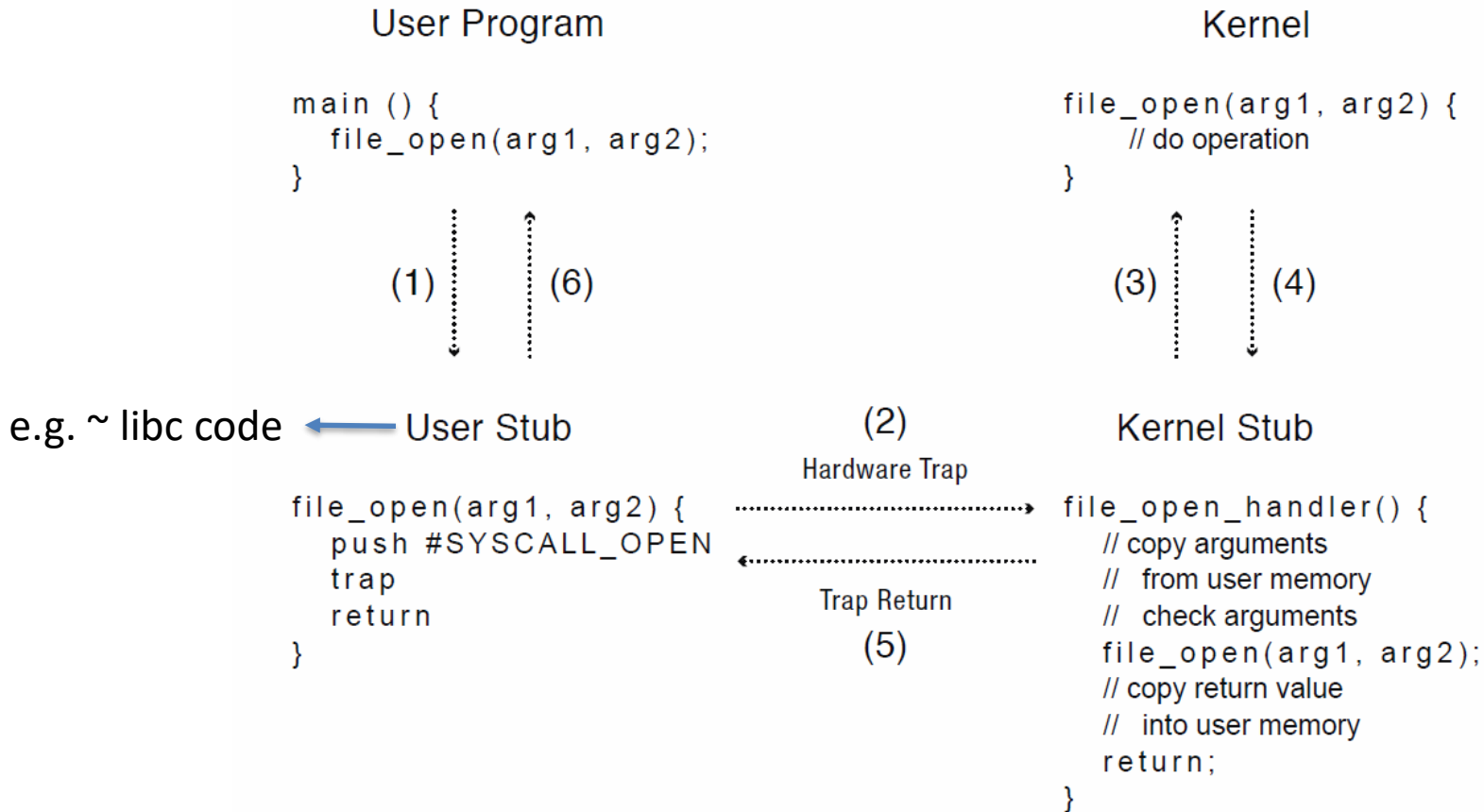
Upcall: Before



Upcall: During



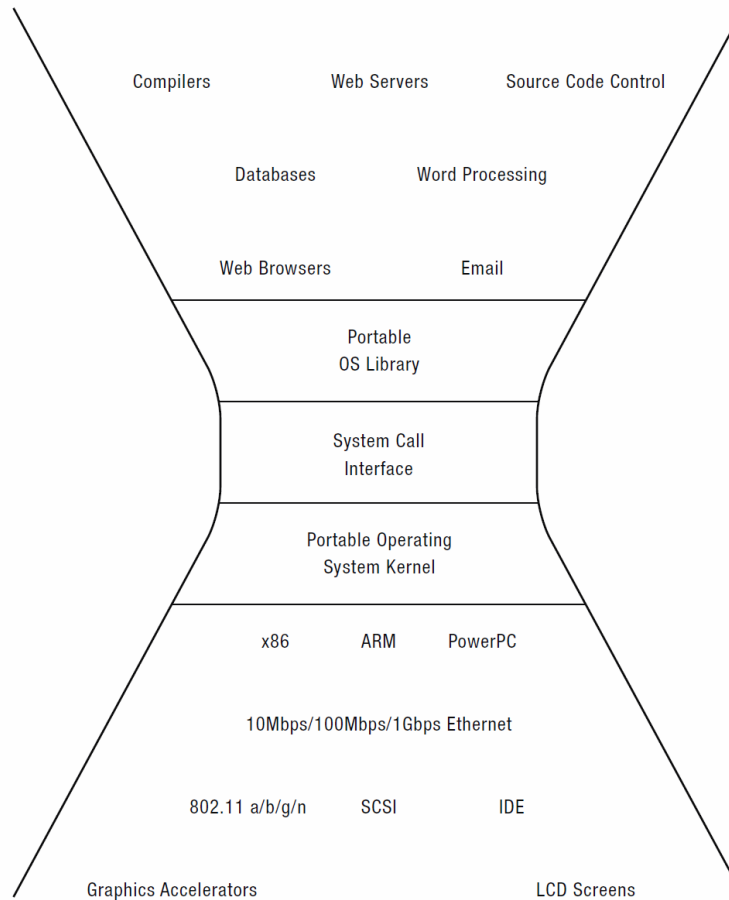
Making system calls secure



Kernel System Call Handler

- Locate arguments
 - In registers or on user stack
 - *Translate* user addresses (VA) into kernel addresses (PA)
- Copy arguments
 - From user memory into kernel memory
 - Protect kernel from malicious code evading checks
 - Time-of-check vs. Time-of-use (TOCTOU) attack avoided
- Validate arguments
 - Protect kernel from errors in user code
- Copy results back into user memory
 - *Translate* kernel addresses into user addresses

Genius of OS software stack



One Implication of this

- Get to choose where to put functionality
- User-level process
 - Unix: user-level shell, login
- User-level library
 - Unix: lib.c (I/O, fork/exec, ...)
- OS kernel
 - File system, network stack, etc

Next Week

- Threads
- Read Chap. 4 OSPP